



**User Manual – AS5x40/AS5x45-AB-v2.1**

# **AS5x40/AS5x45**

**10-bit Rotary Position Sensor with Digital Angle  
(Interface), ABI, UVW and PWM output**



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## Revision History

| Revision | Date       | Owner | Description             |
|----------|------------|-------|-------------------------|
| 1.0      | 01.10.2009 |       | Initial revision        |
| 1.3      | 05.07.2013 | azen  | Updated to new template |
| 1.4      | 09.08.2013 | azen  | Minor corrections       |

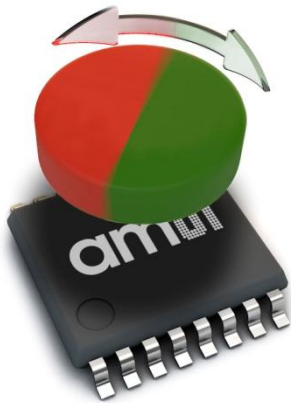


## 1 General Description

The AS5x40/AS5x45 series are contactless magnetic position sensors for accurate angular measurement over a full turn of 360°. They are system-on-chip, combining integrated Hall elements, analog front end and digital signal processing in a single device.

To measure the angle, only a simple two-pole magnet, rotating over the center of the chip, is required. The magnet may be placed above or below the IC. (See Figure 1:)

Figure 1:  
Rotary Position Sensor AS5040 + Magnet



## 2 The AS5040 adapter board

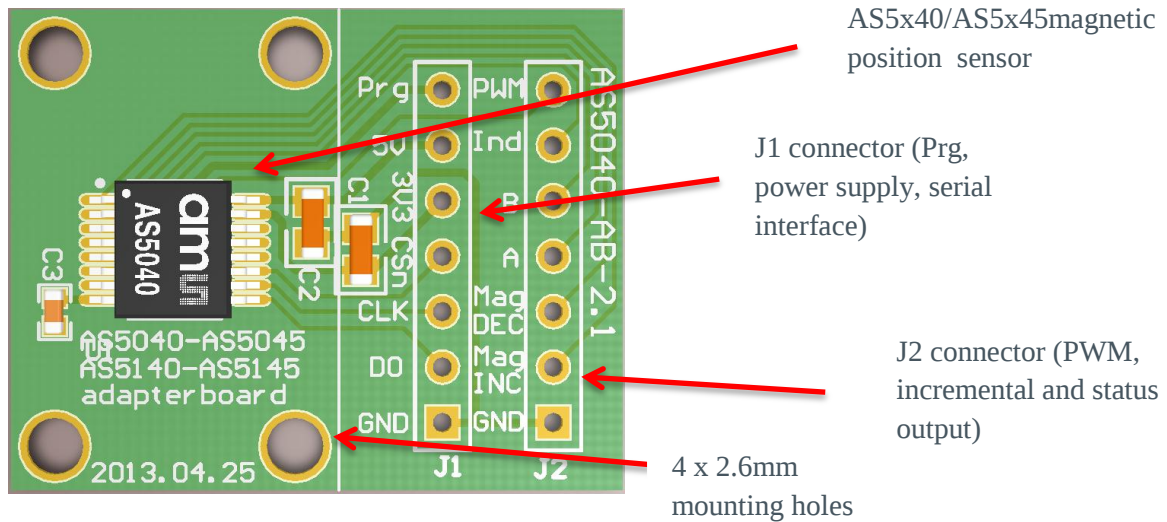
The AS5040 adapter board is a simple circuit allowing test and evaluation of the AS5x40/AS5x45 position sensor without building a test fixture or PCB.

### 2.1 Board description

The PCB can be used as standalone unit or attached to a microcontroller. The standalone operation requires a 5V power supply only; the magnet's angle can be read on the PWM or analog output. (See Figure 2:).



Figure 2:  
AS5040 Adapterboard

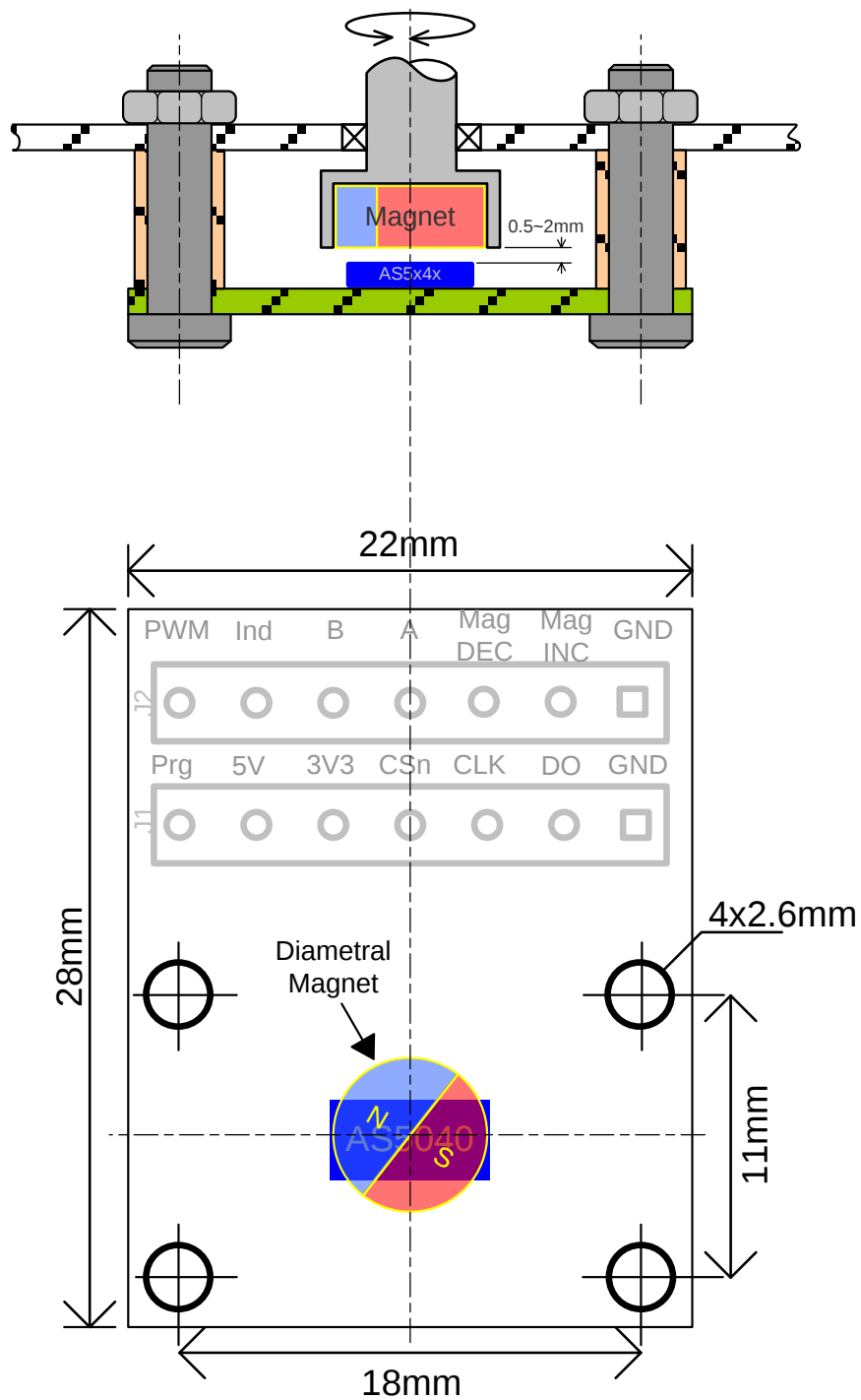


## 2.2 Mounting the AS5040 adapter board

A diametric magnet must be placed over on under the AS5x40/AS5x45 sensor and should be centered on the middle of the package with a tolerance of 0.5mm.

The airgap between the magnet and the sensor casing should be maintained in the range 0.5mm~2mm. The magnet holder must not be ferromagnetic. Materials as brass, copper, aluminum, stainless steel are the best choices to make this part. (See Figure 3:)

Figure 3:  
AS5040 adapter board mounting and dimension



### 3 AS5040 Adapterboard and pinout

The Adapterboard Pinout is shown below.

Figure 4:  
AS5040 adapter board connectors and sensor pinout

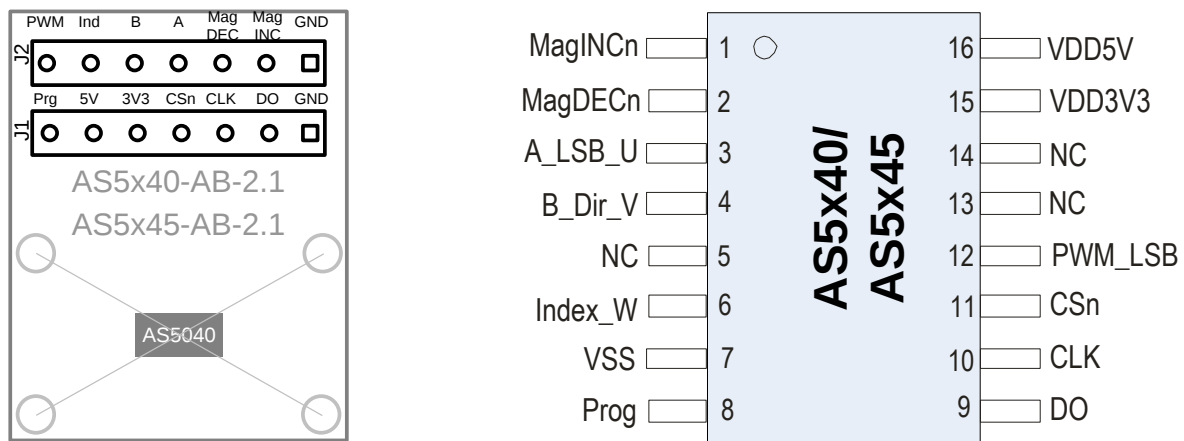


Table 1:  
Pin description

| Pin#<br>Board | Pin#<br>AS5x40<br>AS5x45 | Symbol<br>Board | Type     | Description                                                                                                                                               |
|---------------|--------------------------|-----------------|----------|-----------------------------------------------------------------------------------------------------------------------------------------------------------|
| JP1 - 1       | 7                        | GND             | S        | Supply ground                                                                                                                                             |
| JP1 - 2       | 9                        | DO              | DO_T     | <b>Data Output</b> of Synchronous Serial Interface                                                                                                        |
| JP1 - 3       | 10                       | CLK             | DI_ST    | <b>Clock</b> Input of Synchronous Serial Interface; Schmitt-Trigger input                                                                                 |
| JP1 - 4       | 11                       | CSn             | DI_PU_ST | <b>Chip Select</b> , active low; Schmitt-Trigger input, internal pull-up resistor (~50kΩ) connect to VSS in incremental mode                              |
| JP1 - 5       | 15                       | 3V3             | S        | 3V-Regulator Output                                                                                                                                       |
| JP1 - 6       | 16                       | 5V              | S        | 5V Supply                                                                                                                                                 |
| JP1 - 7       | 8                        | Prg             | DI_PD    | OTP <b>Programming</b> Input and Data Input for Daisy Chain mode. Internal pull-down resistor (~74kΩ). May be connected to VSS if programming is not used |
| JP2 - 1       | 7                        | GND             | S        | Supply ground                                                                                                                                             |
| JP2 - 2       | 1                        | MagINC          | DO_OD    | Magnet Field <b>Magnitude IN</b> crease; active low, indicates a distance reduction between the magnet and the device surface.                            |
| JP2 - 3       | 2                        | MagDEC          | DO_OD    | Magnet Field <b>Magnitude DE</b> crease; active low, indicates a distance increase between the device and the magnet                                      |
| JP2 - 4       | 3                        | A               | DO       | AS5040 – AS5140 – AS5145 (programmed) only<br>Mode1.x: Quadrature <b>A</b> channel<br>Mode2.x: <b>Least Significant Bit</b>                               |



| Pin#<br>Board | Pin#<br>AS5x40<br>AS5x45 | Symbol<br>Board | Type | Description |
|---------------|--------------------------|-----------------|------|-------------|
|---------------|--------------------------|-----------------|------|-------------|

*Mode3.x: U signal (phase1)*

|         |    |     |    |                                                                                                                                                                                                                                                                                                                        |
|---------|----|-----|----|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| JP2 - 5 | 4  | B   | DO | <i>AS5040 – AS5140 – AS5145 (programmed) only</i><br><i>Mode1.x: Quadrature B channel quarter period shift to channel A.</i><br><i>Mode2.x: Direction of Rotation</i><br><i>Mode3.x: V signal (phase2)</i>                                                                                                             |
| JP2 - 6 | 6  | Ind | DO | <i>AS5040 – AS5140 – AS5145 (programmed) only</i><br><i>Mode1.x and Mode2.x : Index signal indicates the absolute zero position</i><br><i>Mode3.x: W signal (phase3)</i><br><i>AS5045 – AS5145 (unprogrammed)</i><br><i>Mode input, connect to VDD5 (Fast mode) or GND (Slow mode); do not change during operation</i> |
| JP2 - 7 | 12 | PWM | DO | Pulse Width Modulation of approx. 1kHz; <b>LSB</b> in <i>Mode3.x</i>                                                                                                                                                                                                                                                   |

|            |       |                           |      |                           |
|------------|-------|---------------------------|------|---------------------------|
| Pin types: | DO_OD | digital output open drain | S    | supply pin                |
|            | DI_PD | digital input pull-down   | DO_T | digital output /tri-state |
|            | DI_PU | digital input pull-up     | ST   | schmitt-trigger input     |
|            | DI    | digital input             | DO   | digital output            |

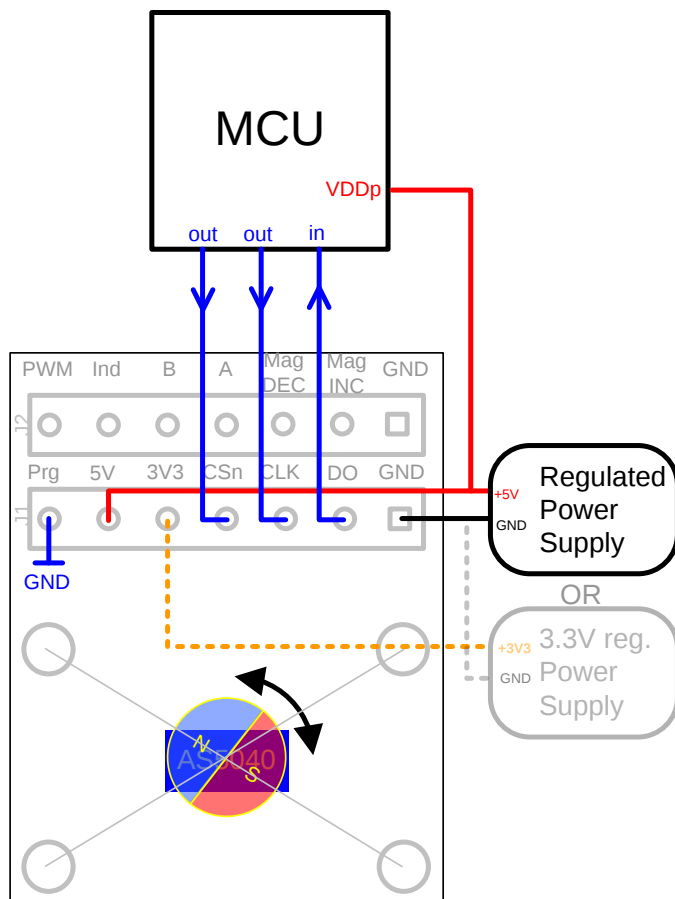
## 4 Operation cases

The most complete and accurate solution for a MCU to read the angle of a magnet is the serial interface.

## 4.1 Standalone SSI output mode

The serial word contains 16 bits for AS5x40 or 18 bits for AS5x45 and consists of 10 bit (AS5x40) or 12 bit (AS5x45) angle value and some other indicator bits like MagINC, MagDEC, which can be read at the same time.

Figure 5:  
Using the analog output with the adapter board



## 4.2 Standalone PWM output mode

The AS5040 provides a pulse width modulated output (PWM), whose duty cycle is proportional to the measured angle. The PWM signal (J2 pin #7) with a period of 1025us (1us step) and 5V pulse voltage can be connected to the capture/timer input of a microcontroller in order to decode the angle value.

Figure 6:  
Using the PWM output with the adapter board

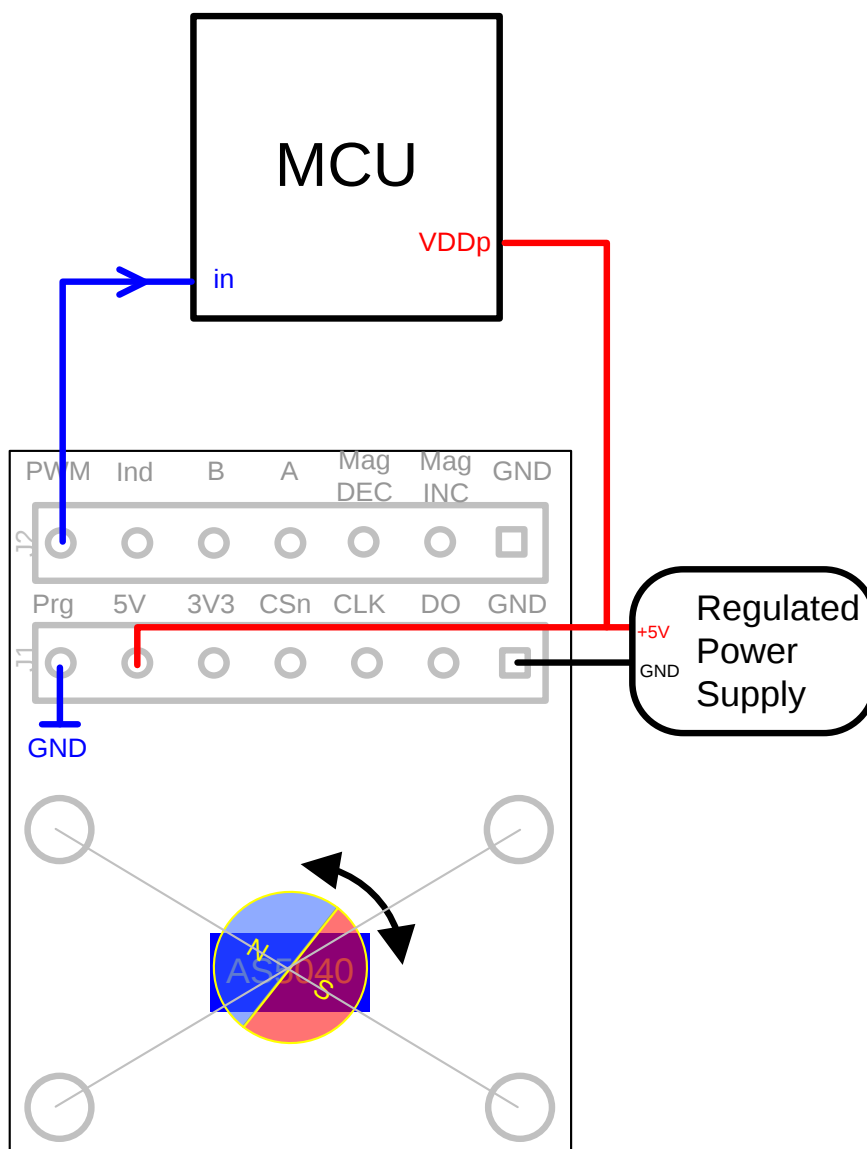
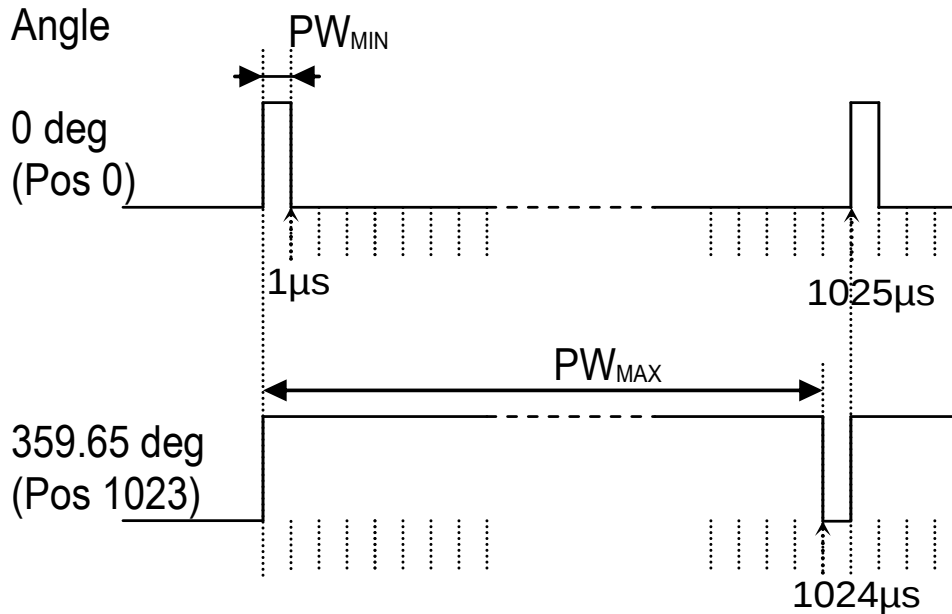


Figure 7:  
PWM duty cycle depending on magnet position



### 4.3 Standalone incremental Output

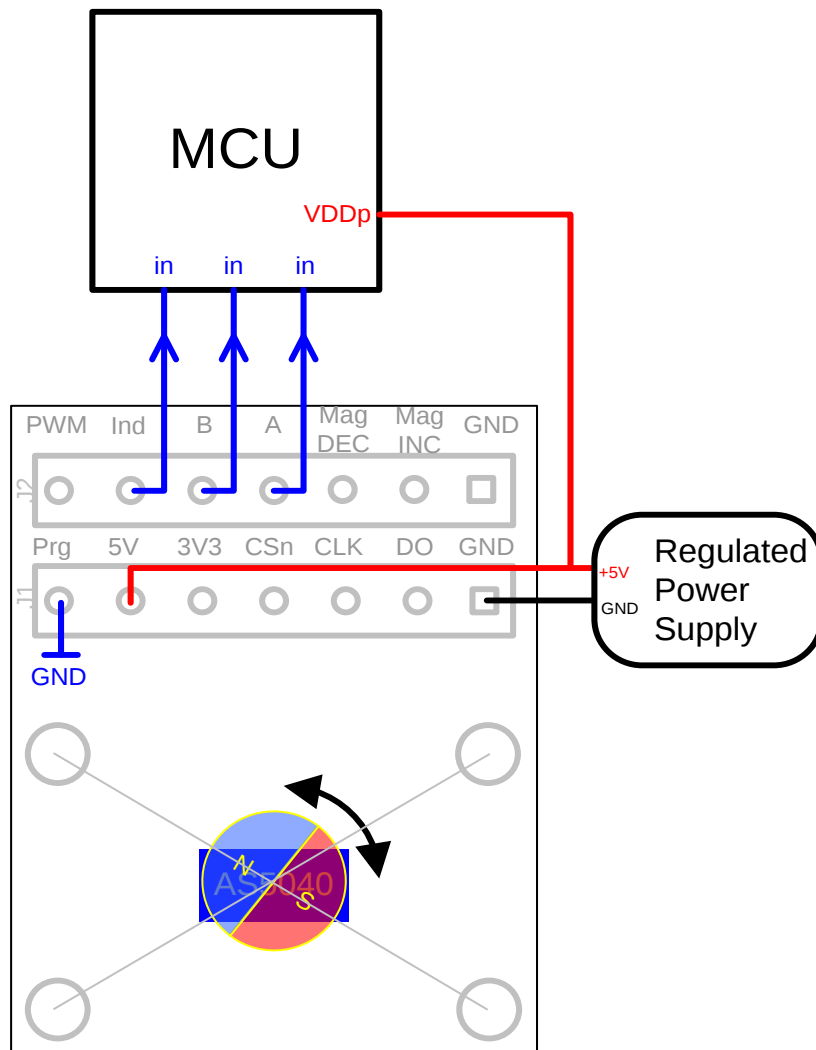
Three different incremental output modes are possible with quadrature A/B being the default mode (two-channel quadrature, step / direction incremental signal (LSB) and the direction bit in clockwise (CW) and counter-clockwise (CCW) direction).

The pre-programmed version AS5145-I10 provides a 10bit and AS5145-I12 a 12bit incremental output.

The AS5045 doesn't provide an incremental output.

For further information, please refer to the datasheet.

Figure 8:  
Using the Incremental output with the adapter board



## 4.4 Daisy chain mode

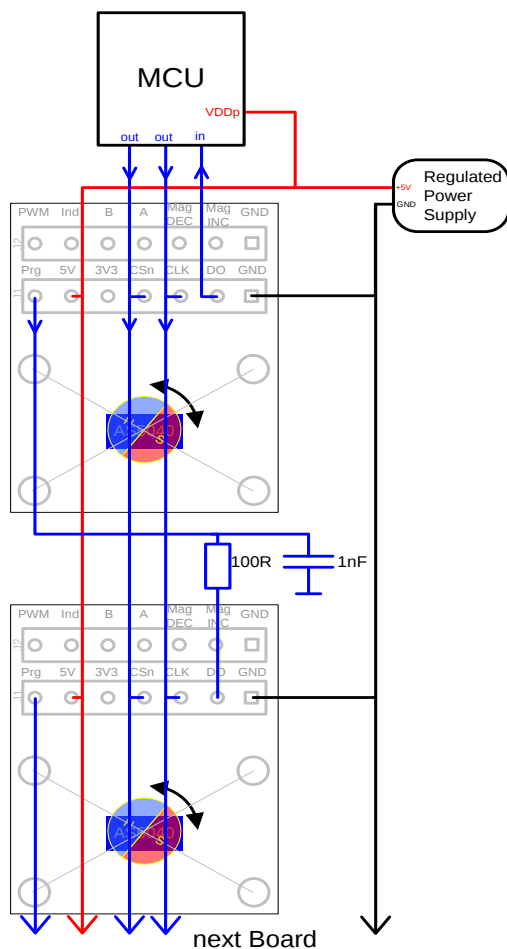
By using more than one adapter board, a setup in daisy chain mode is possible.

**Note:** In this mode capacitor C3 (refer to Fig.12) must be disconnected when using the 1nF capacitor shown in Fig.9 or directly replaced by this capacitor.

The serial data of all connected devices is read from the DO pin of the first device in the chain. The Prog pin of the last device in the chain should be connected to VSS. The length of the serial bit stream increases with every connected device (board) by  $n * (16+1)$  bits.

Due to  $R = 100\Omega$  and  $C = 1\text{nF}$ , the CLK is limited the maximum 1MHz.

Figure 9:  
Using Daisy-Chain mode with the adapter board



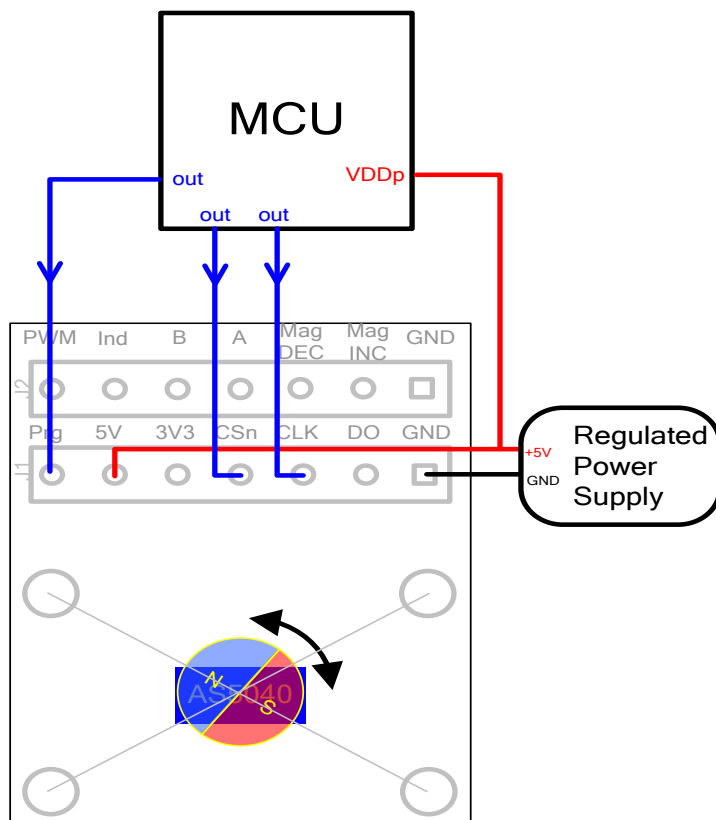
## 5 Programming the AS5040

After power-on, programming the AS5040 is enabled with the rising edge of CSn with Prog = high and CLK = low. 16 bit configuration data must be serially shifted into the OTP register via the Prog-pin. The first “CCW” bit is followed by the zero position data (MSB first / 10 bit for AS5x40 and 12 bit for AS5x45) and some mode settings (please refer to datasheet). Data must be valid at the rising edge of CLK.

After writing data into the OTP register it can be permanently programmed by rising the Prog pin to the programming voltage  $V_{\text{PROG}}$  of 7.3-7.5V. 16 CLK pulses must be applied to program the fuses.

For exiting the programming mode, the chip must be reset by a power-on-reset. The programmed data is available after the next power-up.

Figure 10:  
Programming the AS5040



## 6 AS5040 differences to AS5045

The Table below shows the differences between AS5040 and AS5045

Table 2:  
Differences AS5040/ AS5045

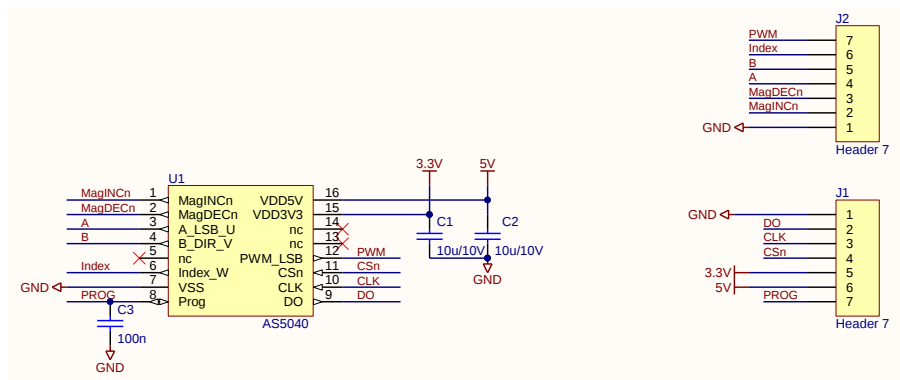
| Building Block                 | AS5045                                                                                                                                       | AS5040                                                                                                                                |
|--------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------|
| Resolution                     | 12bits, 0.088°/step.                                                                                                                         | 10bit, 0.35°/step                                                                                                                     |
| Data length                    | read: 18bits<br>(12bits data + 6 bits status)<br>OTP write: 18 bits<br>(12bits zero position + 6 bits mode selection)                        | read: 16bits<br>(10bits data + 6 bits status)<br>OTP write: 16 bits<br>(10bits zero position + 6 bits mode selection)                 |
| incremental encoder            | Not used<br>Pin 3: not used<br>Pin 4: not used                                                                                               | quadrature, step/direction and BLDC motor commutation modes<br>Pin 3: incremental output A_LSB_U<br>Pin 4: incremental output B_DIR_V |
| Pins 1 and 2                   | MagINCn, MagDECn: same feature as AS5040, additional OTP option for red-yellow-green magnetic range                                          | MagINCn, MagDECn indicate in-range or out-of-range magnetic field plus movement of magnet in z-axis                                   |
| Pin 6                          | MODE pin, switch between fast and slow mode                                                                                                  | Pin 6: Index output                                                                                                                   |
| Pin 12                         | PWM output: frequency selectable by OTP:<br>1µs / step, 4096 steps per revolution, f=244Hz<br>2µs / step, 4096 steps per revolution, f=122Hz | PWM output:<br>1µs / step, 1024 steps per revolution, 976Hz PWM frequency                                                             |
| sampling frequency             | selectable by MODE input pin:<br>2.5kHz, 10kHz                                                                                               | fixed at 10kHz @10bit resolution                                                                                                      |
| Propagation delay              | 384µs (slow mode)<br>96µs (fast mode)                                                                                                        | 48µs                                                                                                                                  |
| Transition noise (rms; 1sigma) | 0.03 degrees max. (slow mode)<br>0.06 degrees max. (fast mode)                                                                               | 0.12 degrees                                                                                                                          |
| OTP programming options        | zero position, rotational direction, PWM disable, 2 Magnetic Field indicator modes, 2 PWM frequencies                                        | zero position, rotational direction, incremental modes, index bit width                                                               |

## 7 AS5040 AB-Hardware

Below the schematic and layout can be found.

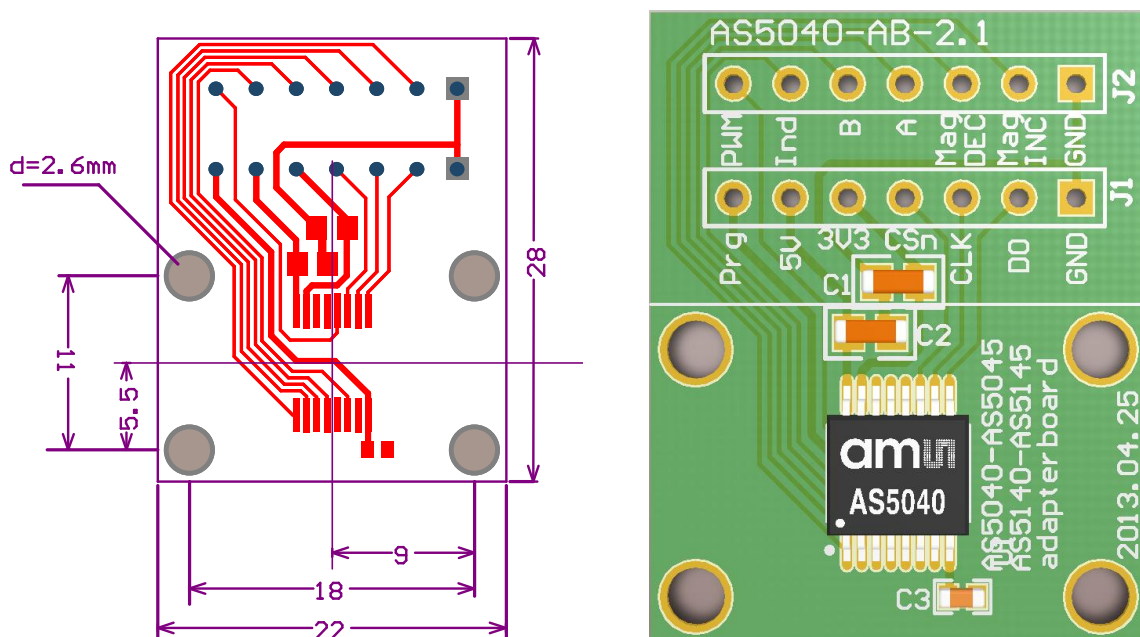
### 7.1 AS5040-AB-2.1 schematics

Figure 11:  
AS5040-AB-2.1-Schematics



### 7.2 AS5040 – AB – 2.1 PCB layout

Figure 12:  
AS5040-AB-2.1-Layout



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