

# TB67H303HG

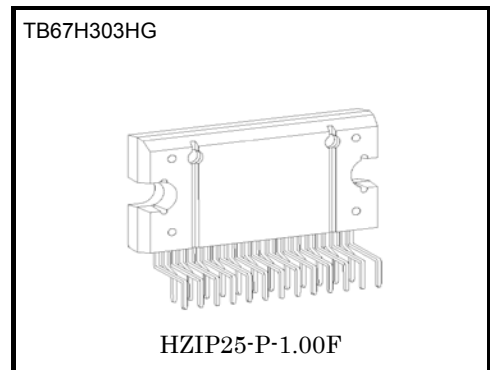
## Full Bridge Driver IC for DC motor

The TB67H303HG is a full bridge driver IC for DC motor adopting MOS in output transistor.

High-power and high-efficient drive is possible by adopting DMOS output driver with low-ON resistance and PWM drive.

### Features

- Full bridge driver IC for DC motor
- $R_{on}$  (upper + lower) =  $0.2\Omega$  (typ.)
- CW/CCW/Short brake/Stop functions
- Standby function
- PWM control (Direct PWM or Constant-current PWM drive)
- Output withstand voltage:  $V_{CC} = 50\text{ V}$
- Output current :  $I_{OUT} = 10.0\text{ A}$  (Absolute maximum ratings, peak)  
 $I_{OUT} = 8.0\text{ A}$  (operating range, maximum value)
- Package : HZIP25-P-1.00F
- Built-in input pull-down resistance :  $100\text{ k}\Omega$  (typ.)
- Output monitor pin (monitor for TSD/ISD) : ALERT1 pin ( $I_{ALERT1}(\text{max}) = 1\text{ mA}$ )
- Output monitor pin (monitor for UVLO) : ALERT2 pin ( $I_{ALERT2}(\text{max}) = 1\text{ mA}$ )
- Single power supply
- Built-in thermal shutdown (TSD) circuit
- Built-in under voltage lock out (UVLO) circuit
- Built-in over-current detection (ISD) circuit



Weight

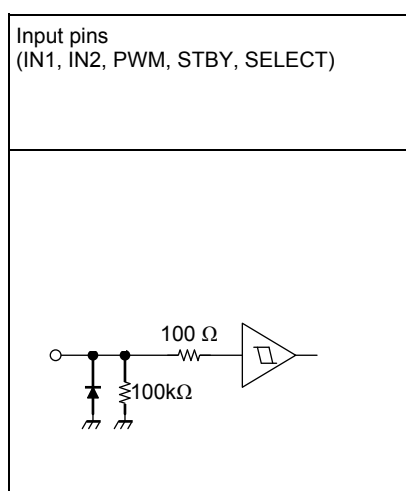
HZIP25-P-1.00F: 7.7g (typ.)

## Pin Functions

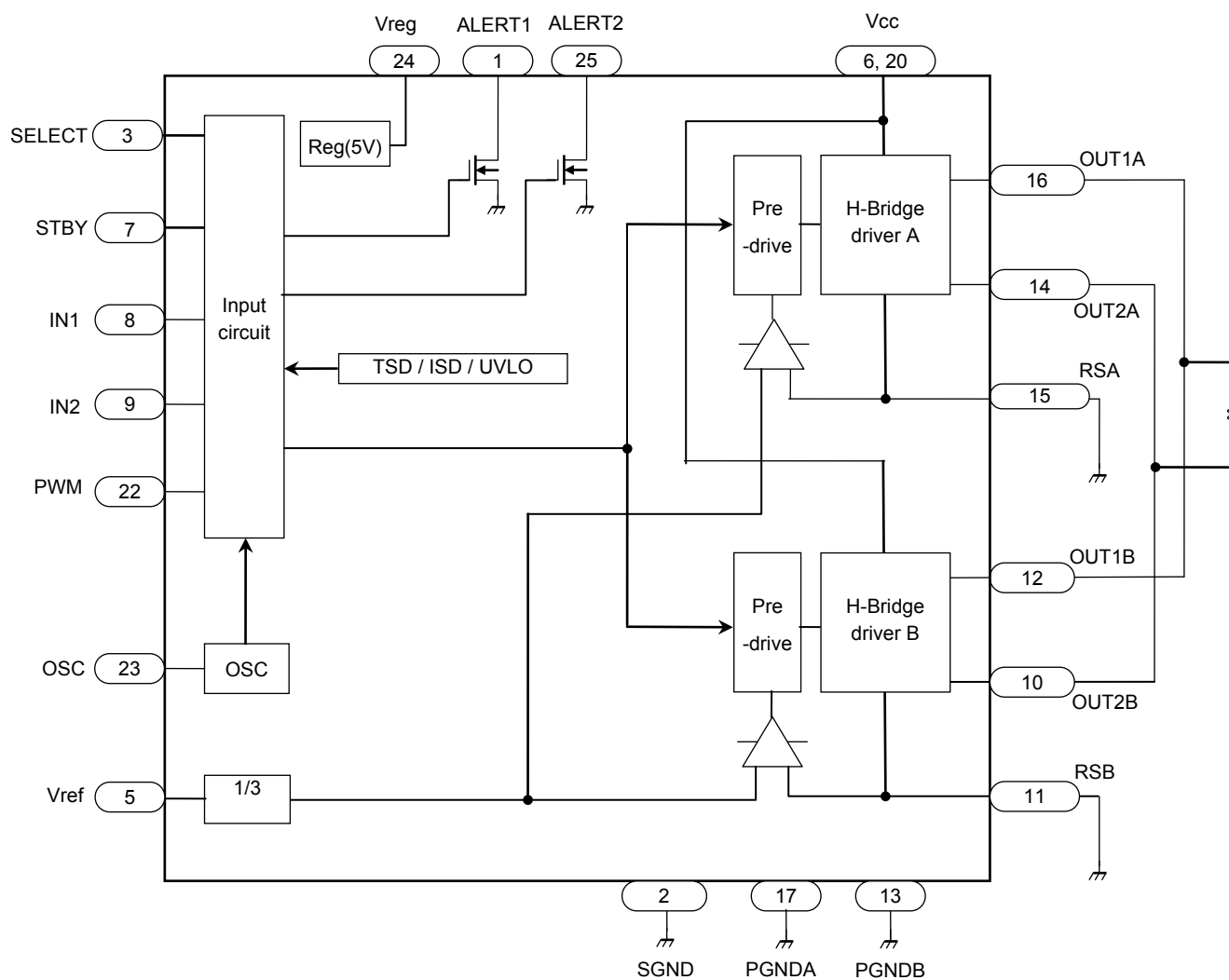
Pin No.	I/O	Symbol	Functional Description	Remark
1	Output	ALERT1	TSD / ISD monitor pin	Pull-up by external resistance
2	—	SGND	Signal ground	
3	Input	SELECT	Select pin for constant-current PWM or direct PWM	
4	—	(TEST1)	Shipping inspection pin	Connect to SGND
5	Input	Vref	Voltage input for 100% current level	
6	Input	Vcc	Power supply	
7	Input	STBY	Standby pin	H; Start, L; Standby
8	Input	IN1	Control input pin 1	
9	Input	IN2	Control input pin 2	
10	Output	OUT2B	Bch output 2	
11	—	RSB	Bch output current detection	
12	Output	OUT1B	Bch output 1	
13	—	PGNDB	Power GND	
14	Output	OUT2A	Ach output 2	
15	—	RSA	Ach output current detection	
16	Output	OUT1A	Ach output 1	
17	—	PGNDA	Power GND	
18	—	(TEST2)	Shipping inspection pin	Connect to SGND
19	—	(TEST3)	Shipping inspection pin	Connect to SGND
20	Input	Vcc	Power supply	
21	—	(TEST4)	Shipping inspection pin	Connect to SGND
22	Input	PWM	PWM signal input pin	
23	—	OSC	Resistor connection pin for internal oscillation setting	
24	Output	Vreg	Control side connection pin for power capacitor	Connecting capacitor to SGND
25	Output	ALERT2	UVLO monitor pin	Pull-up by external resistance

(TEST1), (TEST2), (TEST3) and (TEST4): Shipping inspection pins. They must be connected to SGND.

### <Terminal circuits>



## Block Diagram



## Functions

### I/O functions

#### SELECT = L (Direct PWM mode)

Input				Output		
STBY	IN1	IN2	PWM	OUT1	OUT2	Mode
H	H	H	H	L	L	Short brake
			L			
H	L	H	H	L	H	CW/CCW
			L	L	L	Short brake
H	H	L	H	H	L	CCW/CW
			L	L	L	Short brake
H	L	L	H	OFF (Hi-Z)		Stop
			L			
L	H/L	H/L	H	OFF (Hi-Z)		Standby
			L			

#### SELECT = H (Constant-current PWM mode)

Input				Output		
STBY	IN1	IN2	PWM	OUT1	OUT2	Mode
H	H	H	H	L	L	Short brake
			L			
H	L	H	H	L	H	Constant-current PWM, CW (OUT2→OUT1)
			L	L	L	Short brake
H	H	L	H	H	L	Constant-current PWM, CCW (OUT1→OUT2)
			L	L	L	Short brake
H	L	L	H	OFF (Hi-Z)		Stop
			L			
L	H/L	H/L	H	OFF (Hi-Z)		Standby
			L			

## Selection of direct PWM and constant-current PWM

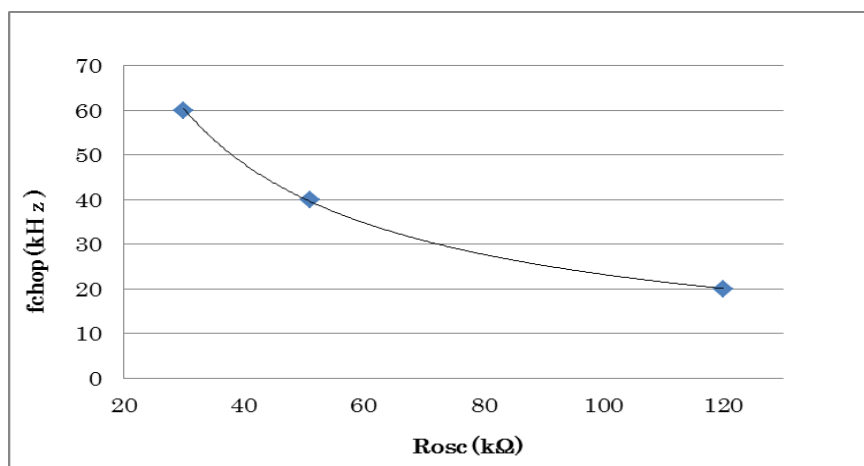
SELECT = L: operating direct PWM, SELECT = H: operating constant-current PWM

- (1) In case of direct PWM:
  - RSA and RSB should be connected to PGND each.
  - Vref should be connected to SGND.
- (2) In case of constant-current PWM:
  - Connect RSA and RSB and then connect to the current detection resistance (RNF).
  - Configuration of output current is as follows;
 
$$I_o = (1/3 \times V_{ref}) \div RNF$$

This system adopts peak current detection. Average current is lower than setting current.  
Set RNF and Vref as follows;  $0.055\Omega \leq RNF \leq 0.25\Omega$ ,  $0.3V \leq V_{ref} \leq 1.95V$

Triangle wave is generated internally by CR oscillation by connecting external resistor to OSC terminal.  
Rosc should be from 30k $\Omega$  to 120k $\Omega$ . The relation of Rosc and fchop is shown in below table and figure. The values of fchop of the below table are design guarantee values. They are not tested for pre-shipment.

Rosc(k $\Omega$ )	fchop(kHz)		
	Min	Typ.	Max
30	-	60	-
51	-	40	-
120	-	20	-



## Direct PWM Control

The motor rotation speed is controllable by the PWM input sent through the PWM pin.

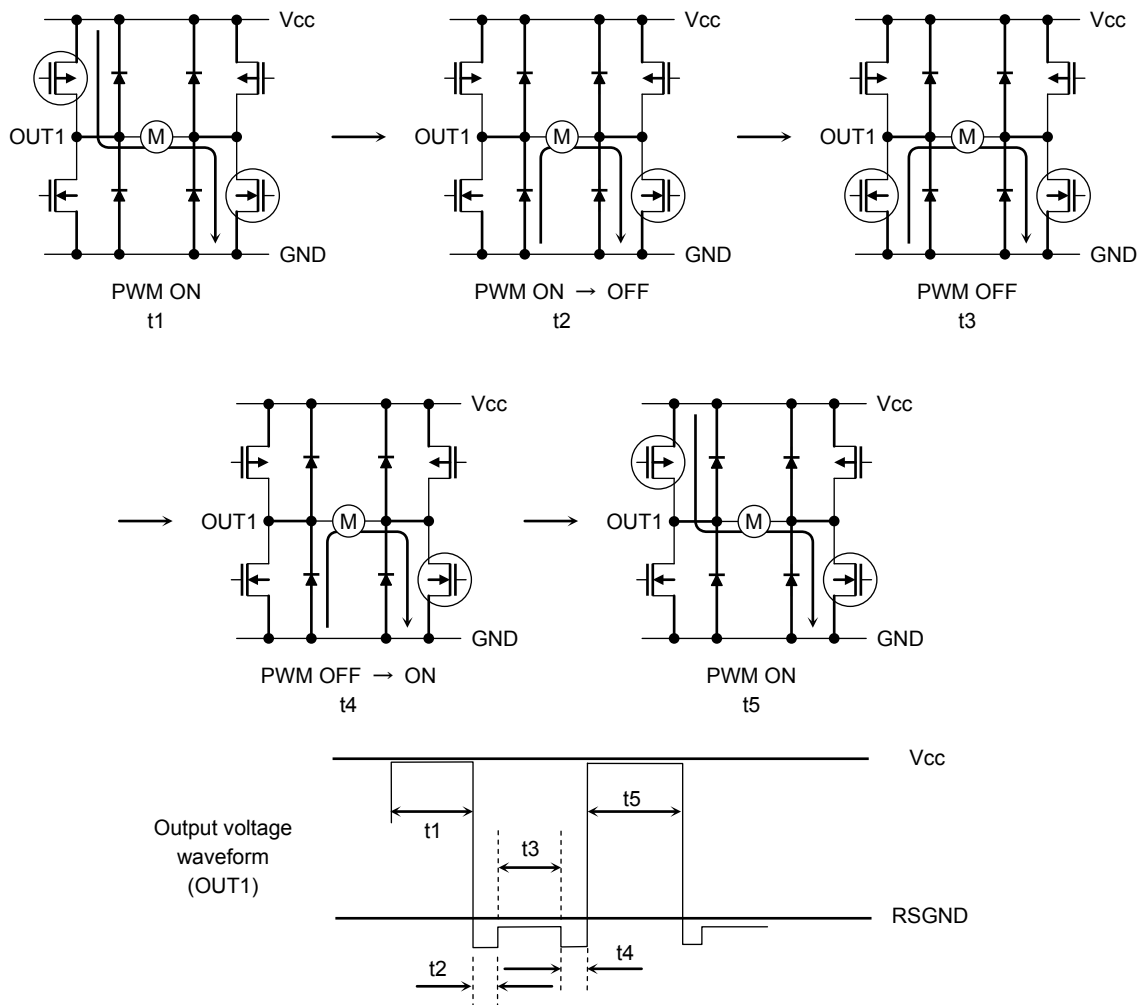
It is also possible to control the motor rotation speed by sending in the PWM signal through not the PWM pin but the IN1 and IN2 pins.

When the motor drive is controlled by the PWM input, the TB67H303HG repeats operating in Normal Operation mode and Short Brake mode alternately.

For preventing the shoot-through current in the output circuit caused by the upper and lower power transistors being turned on simultaneously, the dead time is internally generated at the time the upper and lower power transistors switches between on and off.

This eliminates the need of inserting Off time externally; thus the PWM control with synchronous rectification is enabled.

Note that inserting Off time externally is not required on operation mode changes between CW and CCW, CW and Short Brake, and CCW and Short Brake because of the dead time generated internally.



## Constant-current PWM control

Constant-current PWM control mode is set when SELECT=H.

The TB67H303HG uses a peak current detection technique to keep the output current constant by applying constant voltage through the Vref pin.

The ratio 40% of the fast decay mode is always fixed.

Charge-discharge cycles of PWM drive corresponds to 5 cycles of OSCM. The current is decreasing in the last two OSC cycles; the fast decay mode.

The relation between the master clock frequency (fMCLK), the OSCM frequency (fOSCM) and the PWM frequency (fchop) is shown as follows:

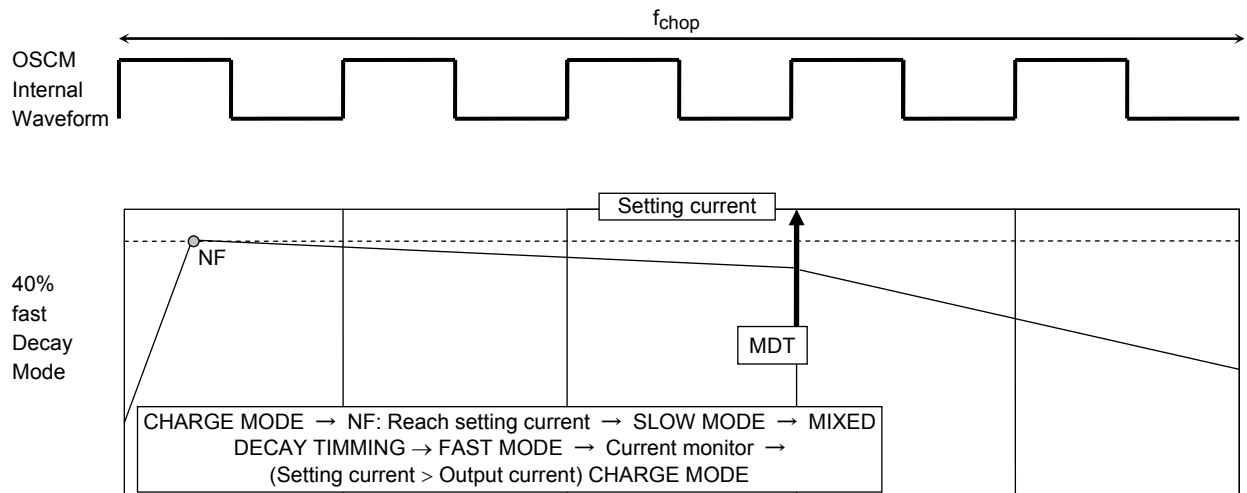
$$f_{OSCM} = 1/20 \times f_{MCLK}$$

$$f_{chop} = 1/100 \times f_{MCLK}$$

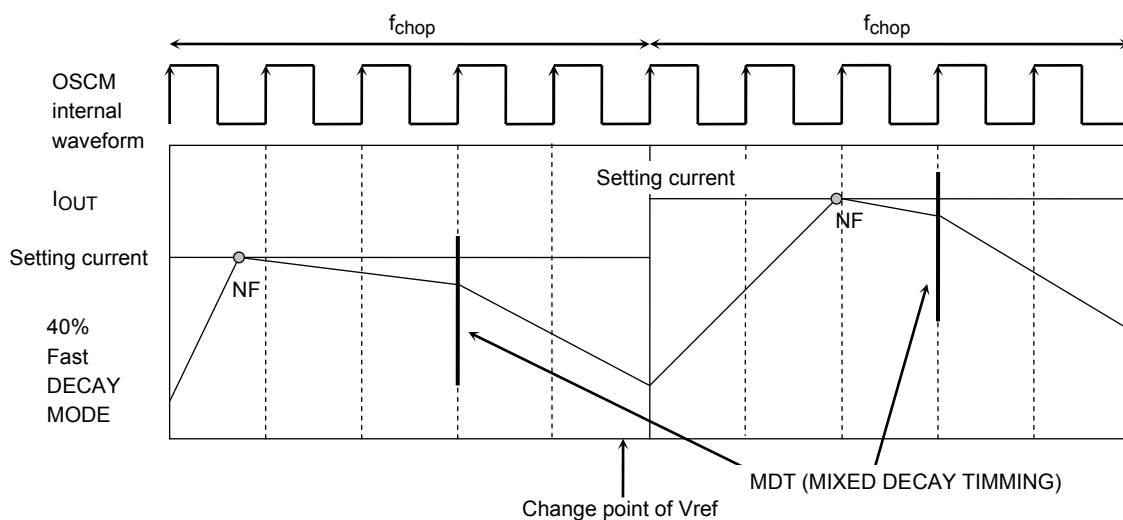
When  $R_{osc}=51k\Omega$ , the master clock=4MHz, OSCM=200kHz, the frequency of PWM( $f_{chop}$ )=40kHz.

NF: Point where output current reaches the setting current.

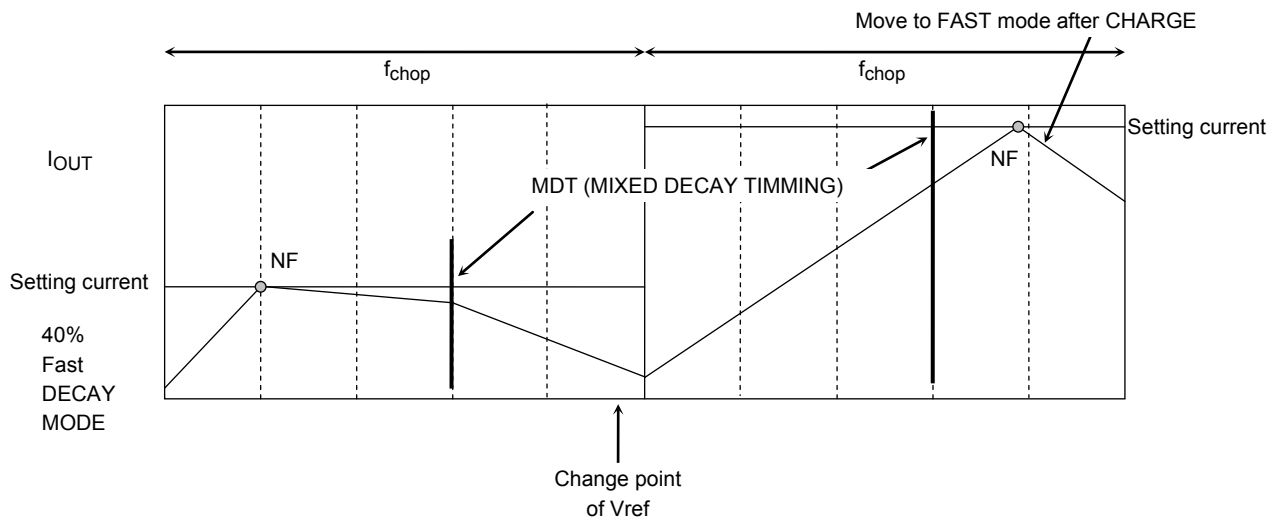
MDT in the below figure indicates the point of MIXED DECAY TIMMING.



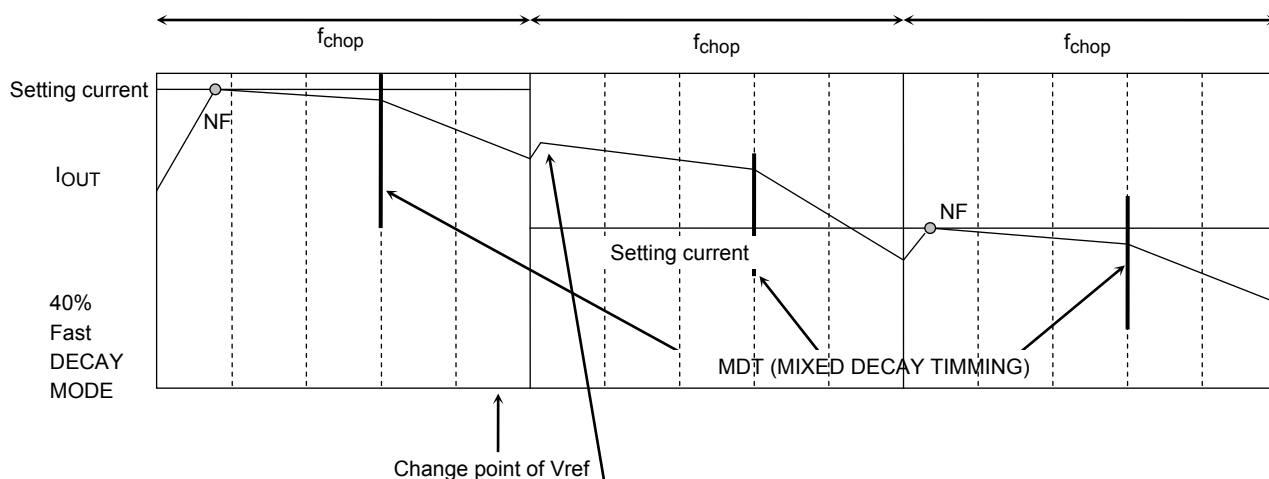
## Current waveform when setting current is changed by changing Vref in the constant-current PWM control mode



- MIXED DECAY TIMMING  $\Rightarrow$  NF point



- Output current of MIXED DECAY MODE > Setting current



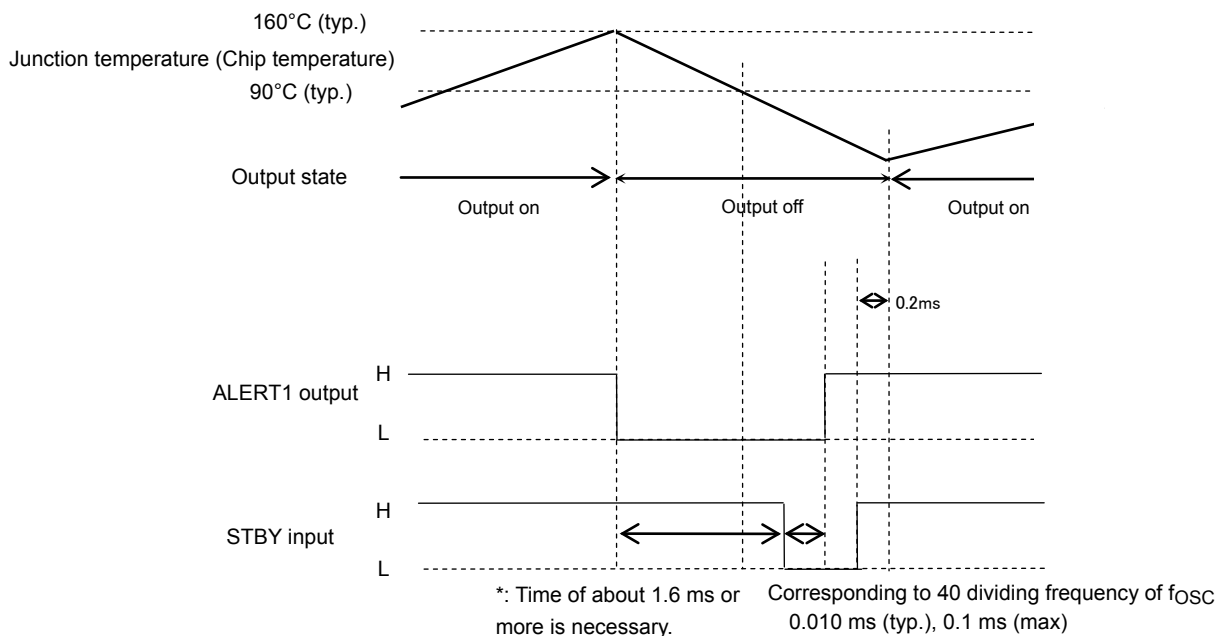
It is charged instantaneously to confirm the current though output current is larger than setting current.



## Thermal Shut-Down circuit (TSD)

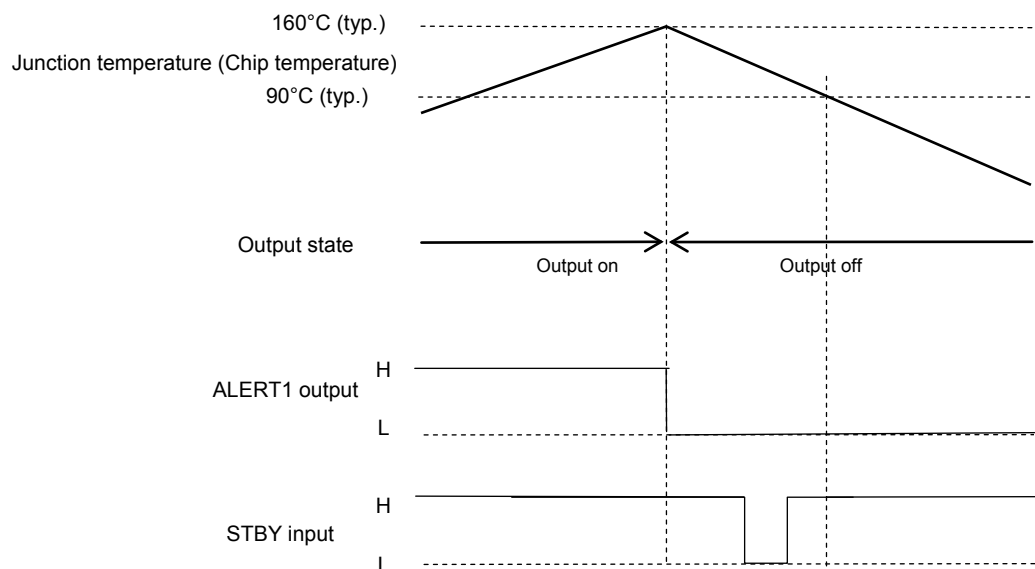
**Latch return** TSD = 160°C (typ.) (Note)

(1) When recovery signal is inputted after the temperature falls lower than recovery temperature (90°C (typ.)) in the below figure (Note)).



The operation returns by programming the STBY as H → L → H shown in above figure or turning on power supply and turning on UVLO function.

(2) When recovery signal is inputted before the temperature falls lower than the recovery temperature (90°C (typ.)) in below figure (Note)).



If STBY is programmed H → L → H shown in the above figure before the temperature falls lower than the recovery temperature (90°C (typ.)) in the above figure (Note)), the operation does not return.

Note: Pre-shipment testing is not performed.

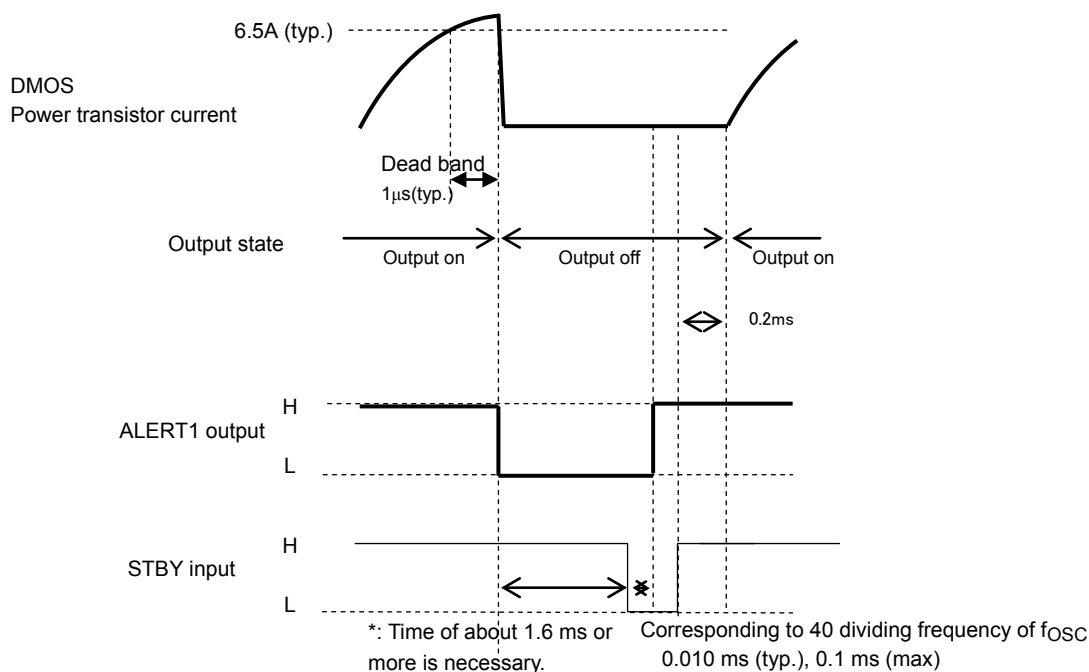
**STBY = L: TSD is not enabled.**

## ISD (Over current detection)

Current that flows through output power MOSFETs are monitored individually. If over-current is detected in at least one of the eight output power MOSFETs, all output power MOSFETs are turned off. Masking term of 1 $\mu$ s or more (typ. when  $R_{osc}=51k\Omega$ ) (Note) should be provided in order to protect detection error by noise. ISD does not work during the masking term. The operation is not returned automatically. It is latched. This function is released by programming STBY H $\rightarrow$ L $\rightarrow$ H.

$$ISD = 6.5 A \quad (\text{Note})$$

## Latch return



The operation returns by programming STBY H $\rightarrow$ L $\rightarrow$ H shown in the above figure or powering on the supply again to drive UVLO.

Note: Pre-shipment testing is not performed.

**STBY = L: ISD is not enabled.**

## ALERT output

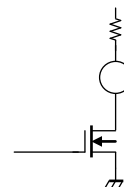
### (1) ALERT 1 (Pin No. 1)

ALERT 1 terminal outputs in detecting either TSD or ISD.

ALERT 1 terminal is connected to power supply externally via pull-up resistance. Spec. is shown below.

$$V_{\text{ALERT}} = 0.5\text{V (max) at } 1\text{mA}$$

TSD	ISD	ALERT 1
Under TSD detection	Under ISD detection	Low
Normal	Under ISD detection	
Under TSD detection	Normal	
Normal	Normal	Z



Applied voltage to pull-up resistance is up to 5.5 V. And conducted current is up to 1 mA.

The voltage of 5 V is recommended to be provided by connecting the external pull-up resistance to Vreg pin.

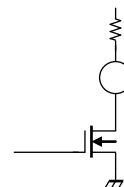
### (2) ALERT 2 (Pin No. 25)

ALERT 2 terminal outputs in detecting UVLO.

ALERT 2 terminal is connected to power supply externally via pull-up resistance. Spec. is shown below.

$$V_{\text{ALERT}} = 0.5\text{V (max) at } 1\text{mA}$$

UVLO	ALERT 2
Under UVLO detection	Low
Normal	Z

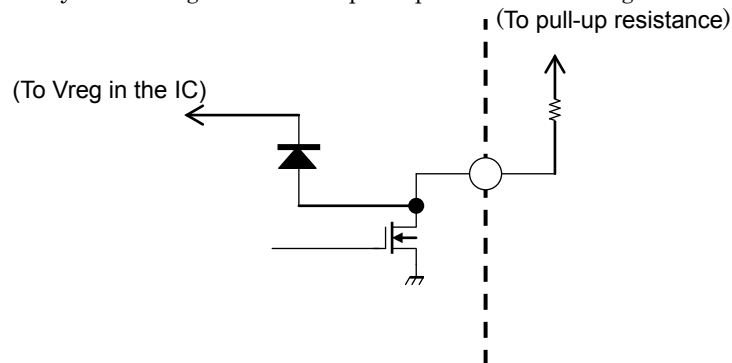


When  $V_{\text{CC}}$  falls to 6.0V (typ.) and UVLO is enabled, output turns off and ALERT 2 outputs low. In case  $V_{\text{CC}}$  falls below 6.0V (typ.), ALERT 2 outputs Hi-Z (High impedance).

The operation returns from Standby mode when  $V_{\text{CC}}$  rises 6.5V (typ.) or more.

Applied voltage to pull-up resistance is up to 5.5 V. And conducted current is up to 1 mA.

The voltage of 5 V is recommended to be provided by connecting the external pull-up resistance to Vreg pin.



### Voltage pull-up of ALERT 1 and ALERT 2 pins

- It is recommended to pull-up the voltage to Vreg pin.
  - In case of pulling up the voltage of except 5 V (for instance, 3.3 V etc.), it is recommended to use other power supply (ex. 3.3 V) while  $V_{\text{CC}}$  outputs within the operation range. When  $V_{\text{CC}}$  decreases lower than the operation range and Vreg decreases from 5 V to 0 V under the condition that other power supply is used to pull-up voltage, the current continues to conduct from other power supply to the IC inside through the diode shown in the figure. Though this phenomenon does not cause destruction and malfunction of the IC, please consider the set design not to continue such a state for a long time.
  - As for the pull-up resistance for ALERT 1 and ALERT 2 pins, please select large resistance enough for the conducting current so as not to exceed the standard value of 1 mA.
- Please use the resistance of 30 kΩ or more in case of applying 5 V, and 20 kΩ or more in case of applying 3.3 V.

## Absolute Maximum Ratings (Ta = 25°C)

Characteristic	Symbol	Rating	Unit
Power supply voltage	V <sub>CC</sub>	50	V
Output current	I <sub>O</sub> (PEAK)	10.0 (Note 1)	A
Drain current (ALERT1, ALERT2)	I (ALERT1)	1	mA
	I (ALERT2)		
Input voltage	V <sub>IN</sub>	6	V
Power dissipation	P <sub>D</sub>	3.2 (Note 2)	W
		40 (Note 3)	
Operating temperature	T <sub>opr</sub>	−30 to 85	°C
Storage temperature	T <sub>stg</sub>	−55 to 150	°C

Note 1: Absolute Maximum Rating of output current per one channel is 5A, therefore, that of a parallel connection of two outputs on the outside of the IC is 10A.

Make sure that two outputs are connected in parallel on the outside of the IC and that one pair should be OUT1A and OUT1B and the other should be OUT2A and OUT2B.

Pay attention to wiring of the output terminals because there may be danger of current exceeding the absolute maximum rating 5A per 1 channel because of concentrating current at only one channel if there is a great lack of balance in the wiring length and so on between A phase side and B phase side about the parallel connection wiring of the output terminals on the outside of the IC.

Note 2: Ta = 25°C, No heat sink

Note 3: Ta = 25°C, with infinite heat sink

The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these absolute maximum ratings.

Exceeding the absolute maximum ratings may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.

Please use the IC within the specified operating ranges.

## Operating Range (Ta = −30 to 85°C)

Characteristic	Symbol	Test Condition	Min	Typ.	Max	Unit
Power supply voltage	V <sub>CC</sub>	—	8.0	—	42	V
Output current	I <sub>OUT</sub>	—	—	—	8.0	A
Input voltage	V <sub>IN</sub>	—	0	—	5.5	V
	V <sub>ref</sub>	—	0.3	—	1.95	V
PWM frequency (Input in direct PWM drive)	f <sub>PWM</sub>	duty50% IN1, IN2, PWM	—	—	100	kHz
Chopping frequency	f <sub>chop</sub>	In constant-current PWM mode Refer to page 5.	20	40	60	kHz

Note: Same voltage should be applied to two V<sub>CC</sub> pins.

The maximum current of the operating range can not be necessarily conducted depending on various conditions because output current is limited by the power dissipation P<sub>D</sub>.

Make sure to avoid using the IC in the condition that would cause the temperature to exceed T<sub>j</sub> (avg.) = 107°C.

The power supply voltage of 42 V and the output current of 8 A\* are the upper limits of the operating range. Therefore, make sure to have enough margins within these operating ranges (derating design) by considering the power supply variation, the external resistance, and the electrical characteristics of the IC. If either of the voltage or current exceeds the upper limits of the operating range, the IC may not operate normally.

\*8 A: 4 A per one phase. Two phases are connected in parallel.

## Electrical Characteristics (Ta = 25°C, Vcc = 24V)

Characteristic		Symbol	Test Condition	Min	Typ.	Max	Unit
Input voltage	High	V <sub>IN</sub> (H)	IN1, IN2, PWM, STBY, SELECT	2.0	—	5.5	V
	Low	V <sub>IN</sub> (L)		−0.2	—	0.8	
Input hysteresis voltage		V <sub>H</sub>		—	400	—	mV
Input current		I <sub>IN</sub> (H)	V <sub>IN</sub> = 5.0 V	—	50	75	μA
		I <sub>IN</sub> (L)	V <sub>IN</sub> = 0 V	—	—	1	
Vcc supply current		I <sub>CC1</sub>	Stop mode	—	3.2	7	mA
		I <sub>CC2</sub>	CW/CCW mode	—	3.2	7	
		I <sub>CC3</sub>	Short brake mode	—	3.2	7	
		I <sub>CC4</sub>	Standby mode	—	1.9	4	
Vref input circuit	Current limit voltage	V <sub>NF</sub>	V <sub>ref</sub> = 3.0V (Note 1)	0.9	1.0	1.1	V
	Input current	I <sub>IN</sub> (V <sub>ref</sub> )	V <sub>ref</sub> = 3.0V (Note 1)	—	—	1	μA
	Divider ratio	V <sub>ref</sub> /V <sub>NF</sub>	Maximum current: 100%	—	3	—	—
Minimum pulse width		t <sub>WPWMH</sub>	IN1, IN2, PWM	5.0	—	—	μs
		t <sub>WPWML</sub>					
Output residual voltage in logic part		V <sub>OL</sub> ALERT1	I <sub>OL</sub> = 1 mA	—	—	0.5	V
		V <sub>OL</sub> ALERT2					
Internal constant voltage		V <sub>reg</sub>	Standby mode, External capacitor C = 0.1μF	4.5	5.0	5.5	V
Chopping frequency (Constant-current PWM)		f <sub>chop</sub>	R <sub>osc</sub> = 51kΩ	28	40	52	kHz

Note 1: Though V<sub>ref</sub> of the test condition for pre-shipment is 3.0V, make sure to configure V<sub>ref</sub> within the operating range which is written in page 12 in driving the motor.

## Electrical Characteristics (Ta = 25°C, Vcc = 24V)

Characteristic		Symbol	Test Condition	Min	Typ.	Max	Unit
OUT pin	Output ON resistor (Note1) (Note2)	R <sub>ON</sub> U + R <sub>ON</sub> L	I <sub>OUT</sub> = 4 A	—	0.4	0.6	Ω
Output transistor switching characteristics (Note1)		t <sub>r</sub>	V <sub>NF</sub> = 0 V, Output Open	—	50	—	ns
		t <sub>f</sub>		—	500	—	
Output leakage current (Note1)	Upper side	I <sub>LH</sub>	V <sub>CC</sub> = 50 V	—	—	5	μA
	Lower side	I <sub>LL</sub>		—	—	5	

Note 1: The value is indicated per 1ch because pre-shipment testing is performed per 1ch.

Note 2: In using, typical value is 0.2Ω because two output pins are connected in parallel.

Measurement waveform

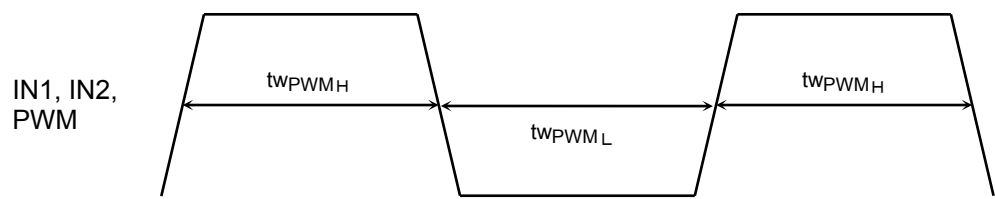


Figure 1 Timing Waveforms and Names

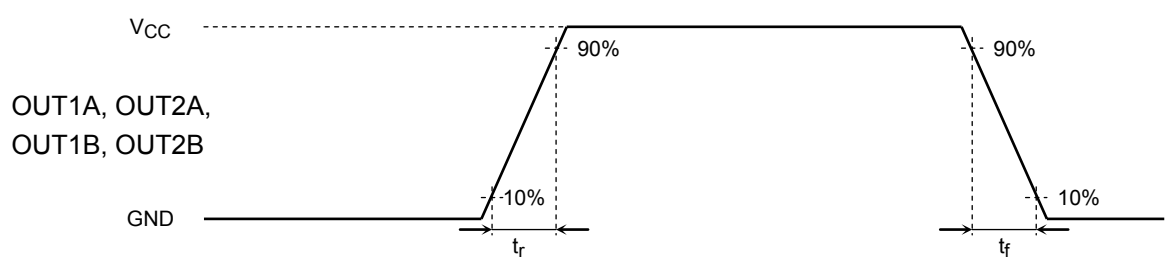
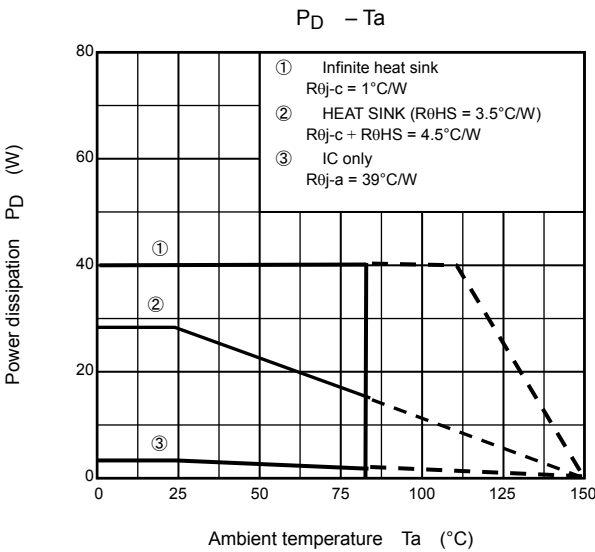


Figure 2 Timing Waveforms and Names

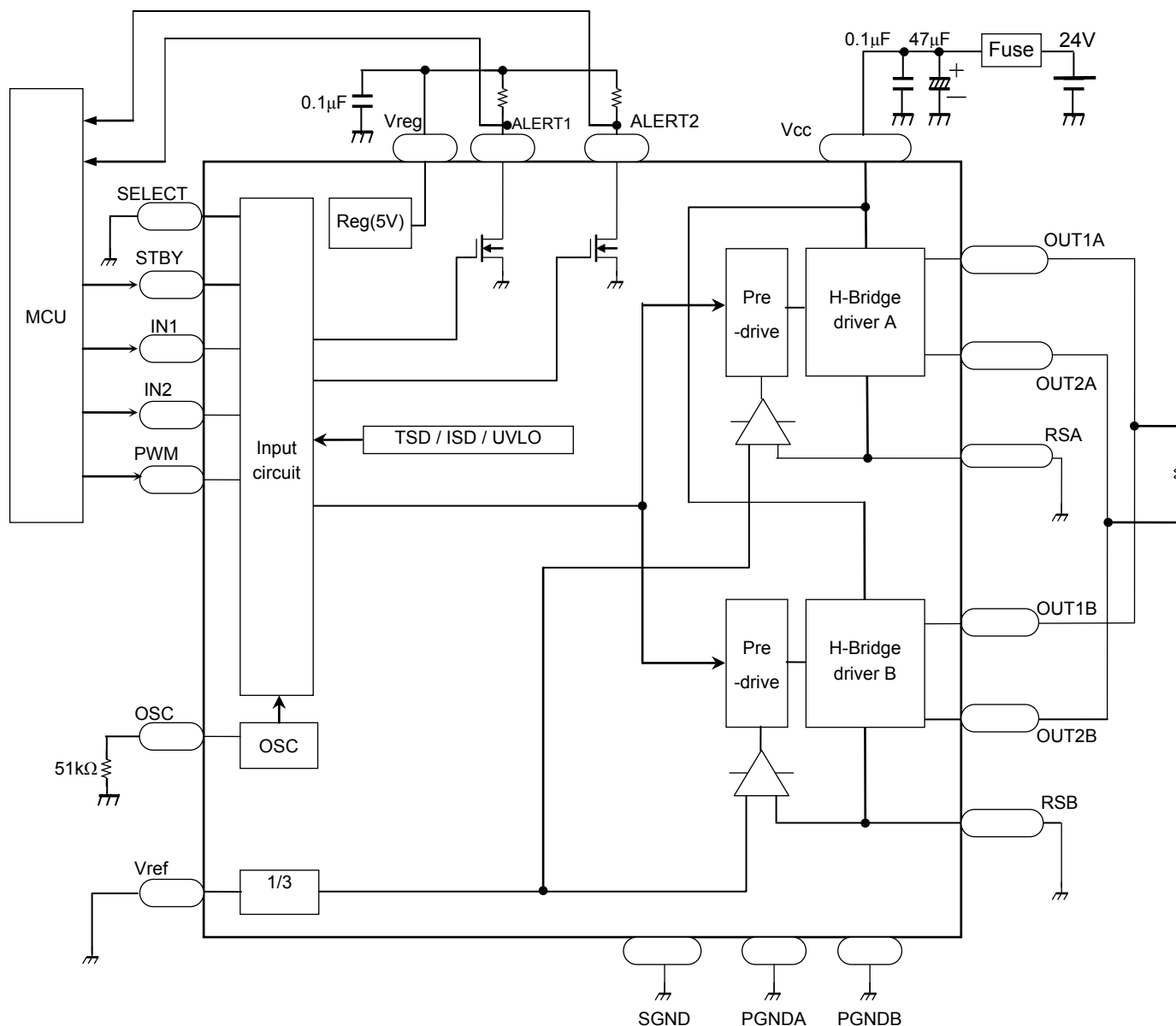
Power dissipation

TB67H303HG



## Application circuit

### (1) Direct PWM

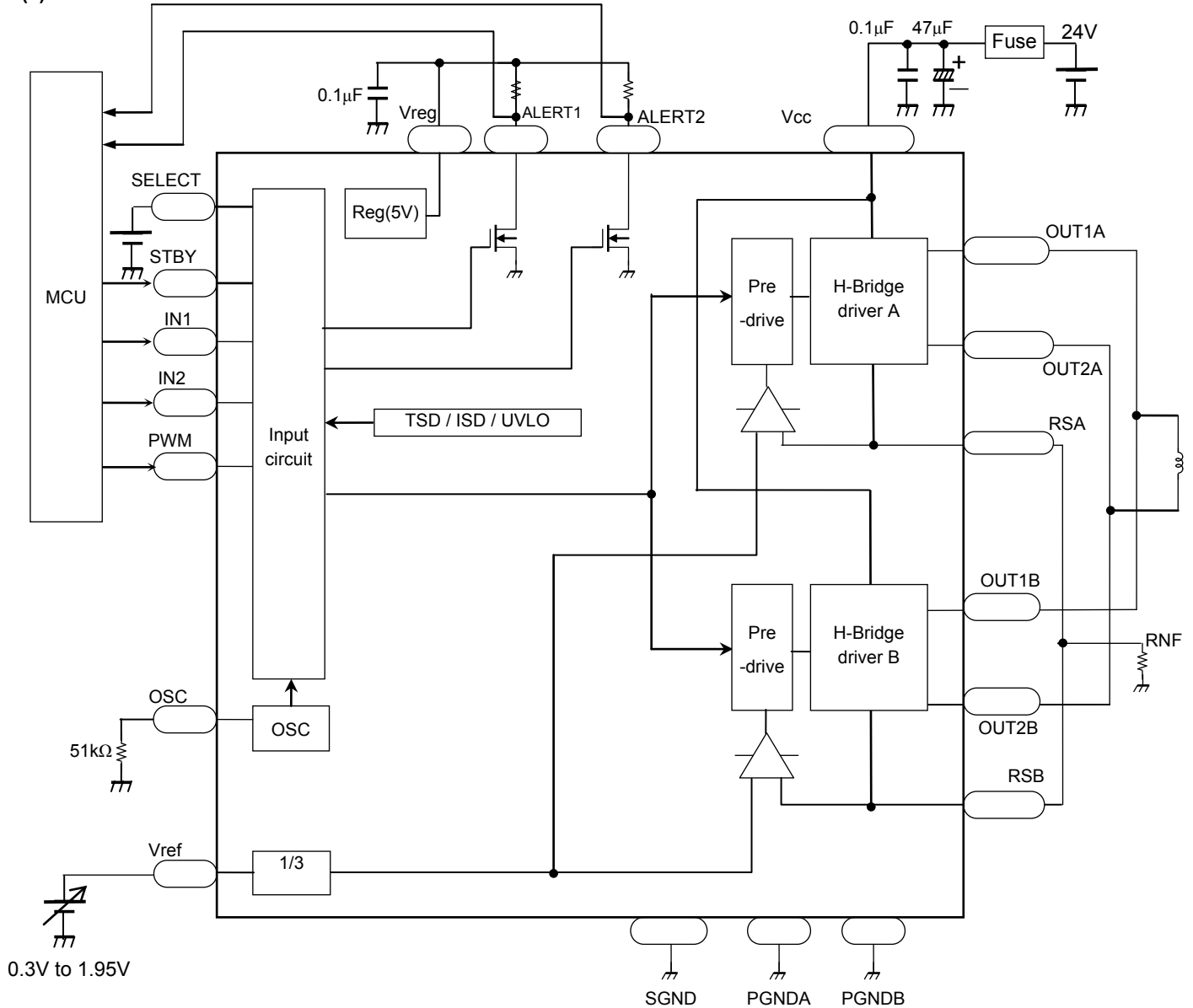


- Set SELECT "L" in direct PWM drive.
- RSA should be connected to PGND. RSB should be connected to PGND.
- Vref should be connected to SGND.



- Note 1: Generally, some ICs are highly sensitive to electrostatic discharge. When handling them, ensure that the environment is protected against electrostatic discharge.
- Note 2: Two outputs are connected in parallel on the outside of the IC.  
Make sure that two outputs are connected in parallel on the outside of the IC and that one pair should be OUT1A and OUT1B and the other should be OUT2A and OUT2B.  
Pay attention to wiring of the output terminals because there may be danger of current exceeding the absolute maximum rating 5A per 1 channel because of concentrating current at only one channel if there is a great lack of balance in the wiring length and so on between A phase side and B phase side about the parallel connection wiring of the output terminals on the outside of the IC.
- Note 3: Capacitors for the power supply lines should be connected as close to the IC as possible.
- Note 4: Pay attention for wire layout of PCB not to allow GND line to have large common impedance.
- Note 5: External capacitor connecting to Vreg should be 0.1μF. Pay attention for the wire between this capacitor and Vreg terminal and the wire between this capacitor and SGND not to be influenced by noise.
- Note 6: The IC may not operate normally when large common impedance is existed in GND line or the IC is easily influenced by noise. For example, if the IC operates continuously for a long time under the circumstance of large current and high voltage, the output according to the input control signal may be different from the I/O function table of this document. And so, the IC may not operate normally. To avoid this malfunction, make sure to conduct Note.2 to Note.5 and evaluate the IC enough before using the IC.
- Note 7: As for a brush motor, the noise, which is generated from the brushes in the motor during the motor rotation, influences on the IC operation. For example, it may cause a malfunction of the ISD circuit and then finally the IC may not work normally. In this case, connect a capacitor between the motor terminals in order to reduce the noise.  
The appropriate value of the capacitor depends on the magnitude of the noise and the inductance of the motor coil. Please determine the value according to each actual equipment and condition. The connecting position of the capacitor should be conformed because the effect of the capacitor is different depending on the position of the capacitor which is near the IC or the motor.

(2) Constant-current PWM



- Set SELECT "H" in constant-current PWM drive.
- Connect RSA and RSB and then connect to the current detection resistance (RNF) shown in above figure.
- Output current is set as follows;

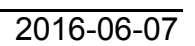
$$I_o = (1/3 \times V_{ref}) \div RNF$$

RNF:  $0.055\Omega \leq RNF \leq 0.25\Omega$ ,  $V_{ref}: 0.3V \leq V_{ref} \leq 1.95V$

Current detection resistance (RNF) should be layout to have same distance from RSA pin and RSB pin and connected as close to them as possible.

- Note 1: Generally, some ICs are highly sensitive to electrostatic discharge. When handling them, ensure that the environment is protected against electrostatic discharge.
- Note 2: Two outputs are connected in parallel on the outside of the IC.  
Make sure that two outputs are connected in parallel on the outside of the IC and that one pair should be OUT1A and OUT1B and the other should be OUT2A and OUT2B.  
Pay attention to wiring of the output terminals because there may be danger of current exceeding the absolute maximum rating 5A per 1 channel because of concentrating current at only one channel if there is a great lack of balance in the wiring length and so on between A phase side and B phase side about the parallel connection wiring of the output terminals on the outside of the IC.
- Note 3: Capacitors for the power supply lines should be connected as close to the IC as possible.
- Note 4: Current detection resistance (RNF) should be connected as close as the IC as possible.
- Note 5: Pay attention for wire layout of PCB not to allow GND line to have large common impedance.
- Note 6: External capacitor connecting to Vreg should be 0.1 $\mu$ F. Pay attention for the wire between this capacitor and Vreg terminal and the wire between this capacitor and SGND not to be influenced by noise.
- Note 7: The IC may not operate normally when large common impedance is existed in GND line or the IC is easily influenced by noise. For example, if the IC operates continuously for a long time under the circumstance of large current and high voltage, the output according to the input control signal may be different from the I/O function table of this document. And so, the IC may not operate normally. To avoid this malfunction, make sure to conduct Note.2 to Note.6 and evaluate the IC enough before using the IC.
- Note 8: As for a brush motor, the noise, which is generated from the brushes in the motor during the motor rotation, influences on the IC operation. For example, it may cause a malfunction of the ISD circuit and then finally the IC may not work normally. In this case, connect a capacitor between the motor terminals in order to reduce the noise.  
The appropriate value of the capacitor depends on the magnitude of the noise and the inductance of the motor coil. Please determine the value according to each actual equipment and condition. The connecting position of the capacitor should be conformed because the effect of the capacitor is different depending on the position of the capacitor which is near the IC or the motor.

Weight: 7.7 g (typ.)  
Unit: mm



## **Notes on Contents**

### **1. Block Diagrams**

Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

### **2. Equivalent Circuits**

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

### **3. Timing Charts**

Timing charts may be simplified for explanatory purposes.

### **4. Application Circuits**

The application circuits shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage.

Toshiba does not grant any license to any industrial property rights by providing these examples of application circuits.

### **5. Test Circuits**

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

## **IC Usage Considerations**

### **Notes on handling of ICs**

- [1] The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.  
Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
  
- [2] Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
  
- [3] If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition.  
Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.
  
- [4] Do not insert devices in the wrong orientation or incorrectly.  
Make sure that the positive and negative terminals of power supplies are connected properly.  
Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.  
In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.

**Points to remember on handling of ICs****(1) Over current Protection Circuit**

Over current protection circuits (referred to as current limiter circuits) do not necessarily protect ICs under all circumstances. If the over current protection circuits operate against the over current, clear the over current status immediately.

Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the over current protection circuit to not operate properly or IC breakdown before operation. In addition, depending on the method of use and usage conditions, if over current continues to flow for a long time after operation, the IC may generate heat resulting in breakdown.

**(2) Thermal Shutdown Circuit**

Thermal shutdown circuits do not necessarily protect ICs under all circumstances. If the thermal shutdown circuits operate against the over temperature, clear the heat generation status immediately.

Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the thermal shutdown circuit to not operate properly or IC breakdown before operation.

**(3) Heat Radiation Design**

In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature ( $T_j$ ) at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into consideration the effect of IC heat radiation with peripheral components.

**(4) Back-EMF**

When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond absolute maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

**(5) Short-circuiting between outputs, air contamination faults, faults due to improper grounding, short-circuiting between contiguous pins**

Utmost care is necessary in the design of the power supply lines, GND lines, and output lines since the IC may be destroyed by short-circuiting between outputs, air contamination faults, or faults due to improper grounding, or by short-circuiting between contiguous pins. They may destroy not only the IC but also peripheral parts and may contribute to injuries for users. Over current may continue to flow in the IC because of this destruction and cause smoke or ignition of the IC. Expect the volume of this over current and add an appropriate power supply fuse in order to minimize the effects of the over current. Capacity of the fuse, fusing time, and the inserting position in the circuit should be configured suitably.

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**Наши контакты:**

**Телефон:** +7 812 627 14 35

**Электронная почта:** [sales@st-electron.ru](mailto:sales@st-electron.ru)

**Адрес:** 198099, Санкт-Петербург,  
Промышленная ул, дом № 19, литера Н,  
помещение 100-Н Офис 331