

MINI-M4™

development board for Stellaris®

The whole Stellaris® development board fitted in DIP40 form factor, containing powerful LX4F230H5QR microcontroller.

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A white, handwritten signature in cursive script, appearing to read 'N. Matic', is positioned on the right side of the page.

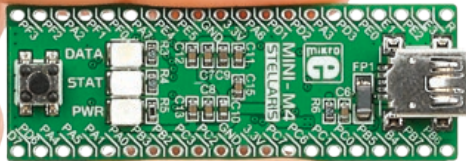
Nebojsa Matic
General Manager

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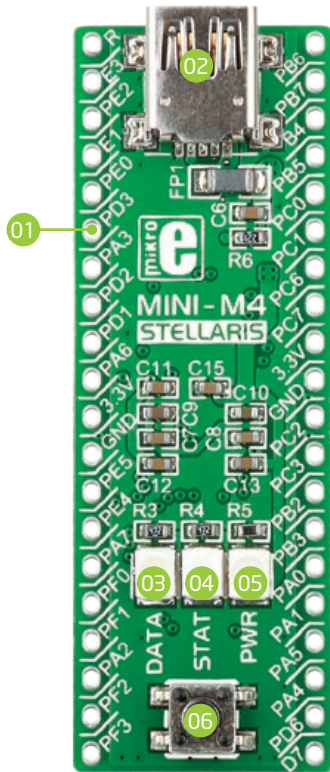
Introduction to MINI-M4 for Stellaris®

Miniature and powerful development tool designed to work as stand alone device or as MCU card in DIP40 socket. MINI-M4 for Stellaris® is pre programmed with USB HID bootloader so it is not necessary to have external programmer. If there is need for external programmer (mikroProg™ for Stellaris®) attach it to MINI-M4 for Stellaris® via pads marked with **PC0** (TCK/SWC), **PC1** (TMS/SWD), **PC2** (TDI), **PC3** (TDO) and **RST#**.



Key features

- 01 Connection Pads
- 02 USB MINI-B connector
- 03 DATA LED
- 04 STAT LED
- 05 POWER supply LED
- 06 Reset button
- 07 Power supply regulator
- 08 Microcontroller LX4F230H5QR
- 09 16 MHz Crystal oscillator
- 10 32.768kHz Crystal oscillator



System Specification



power supply

3.3V via pads or 5V via USB



power consumption

depends on MCU state (max current into 3.3V pad is 800mA)



board dimensions

50.8 x 17.78mm (2 x 0.7")



weight

~6g (0.013 lbs)

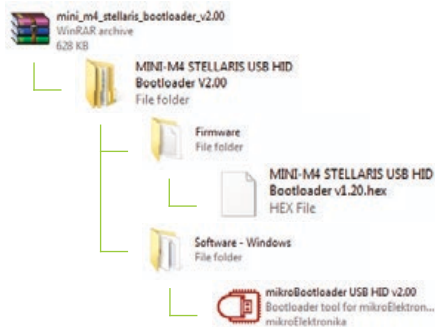
1. Programming with mikroBootloader

You can program the microcontroller with bootloader which is pre programmed into the device by default. To transfer .hex file from a PC to MCU you need bootloader software (**mikroBootloader USB HID**) which can be downloaded from:



http://www.mikroe.com/downloads/get/1937/mi_mini_m4_stellaris_bootloader_v200.zip

After software is downloaded unzip it to desired location and start mikroBootloader USB HID software.



step 1 - Connecting MINI-M4



Figure 1-1: USB HID mikroBootloader window

- 01 To start, connect the USB cable, or if already connected press the **Reset** button on your MINI-M4 board. Click the **"Connect"** button within 5s to enter the bootloader mode, otherwise existing microcontroller program will execute.

step 2 - Browsing for .HEX file



Figure 1-2: Browse for HEX

- 01 Click the **"Browse for HEX"** button and from a pop-up window (**Figure 1-3**) choose the .HEX file which will be uploaded to MCU memory.

step 3 - Selecting .HEX file

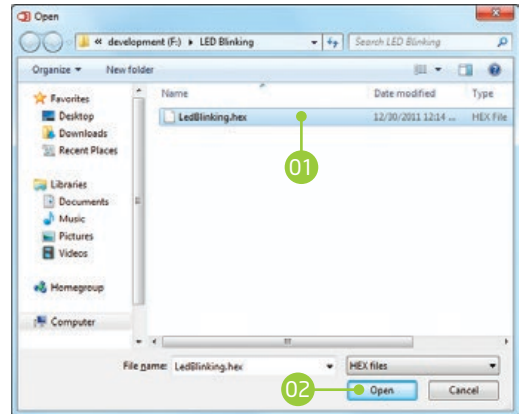


Figure 1-3: Selecting HEX

- 01 Select .HEX file using open dialog window.
- 02 Click the **"Open"** button.

step 4 - Uploading .HEX file

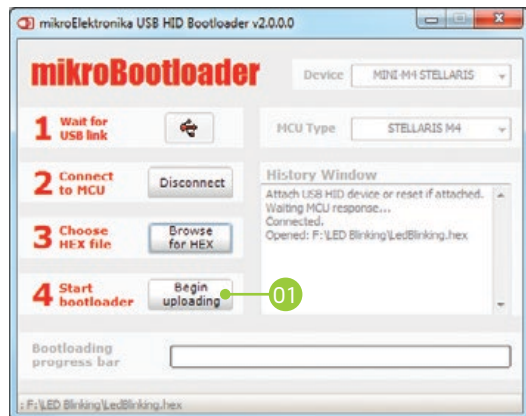


Figure 1-4: Begin uploading

01 To start .HEX file bootloading click the "Begin uploading" button.



Figure 1-5: Progress bar

01 You can monitor .HEX file uploading via progress bar

step 5 - Finish upload

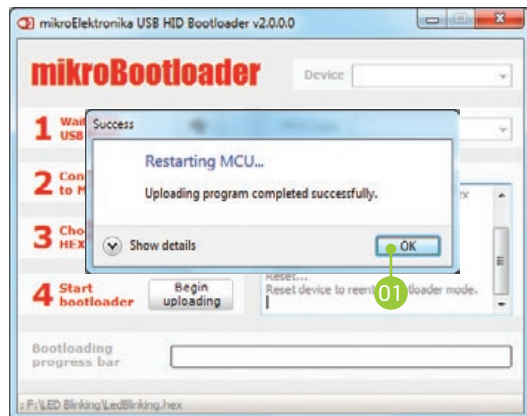


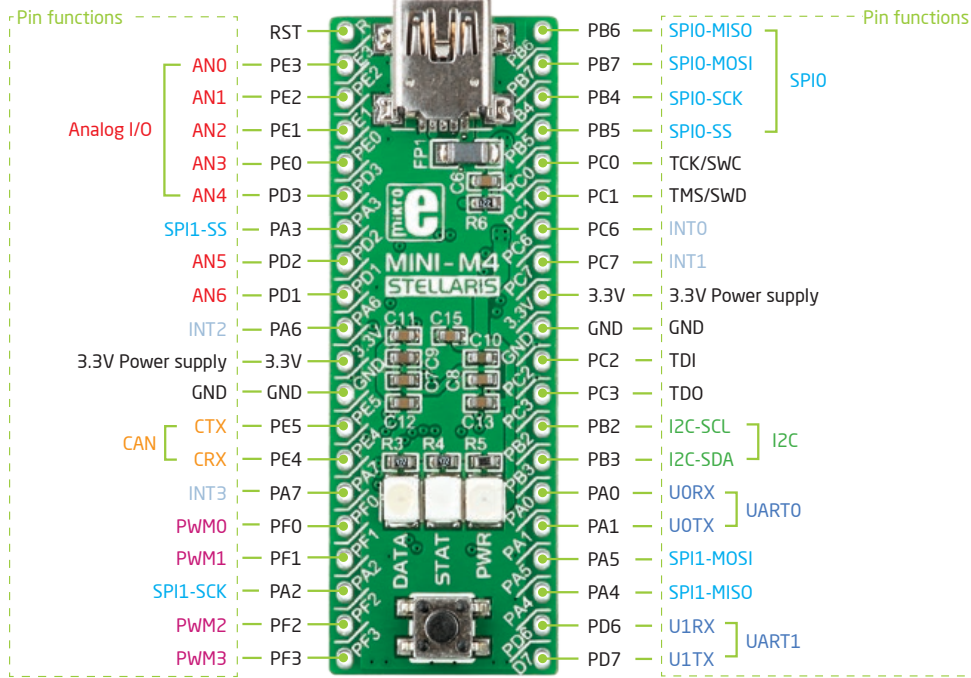
Figure 1-6: Restarting MCU

- 01 Click the **"OK"** button after uploading is finished and wait for 5 seconds. Board will automatically reset and your new program will execute.



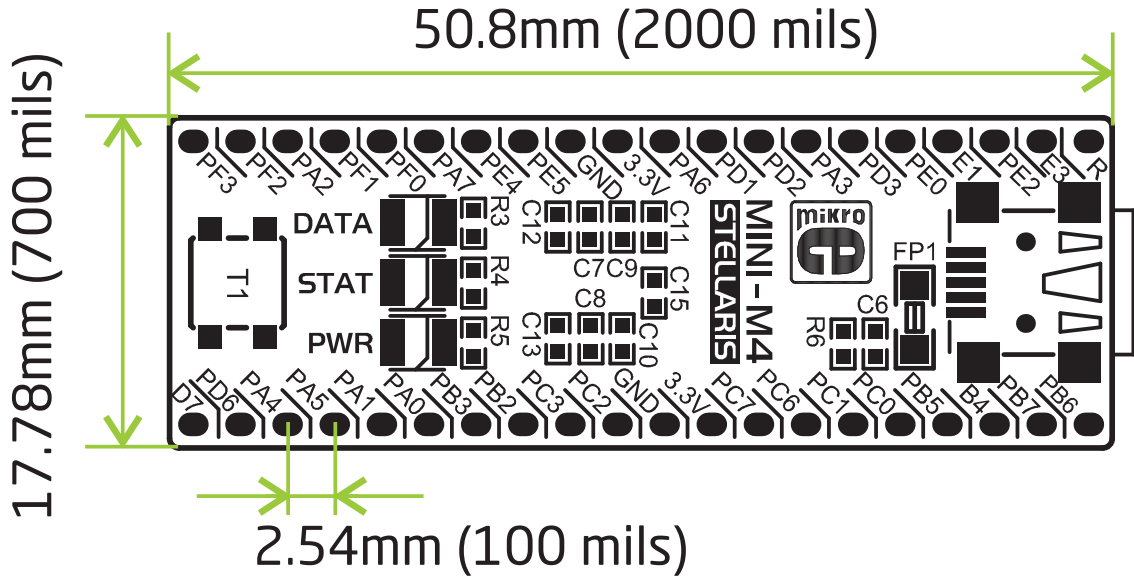
Figure 1-7: mikroBootloader ready for next job

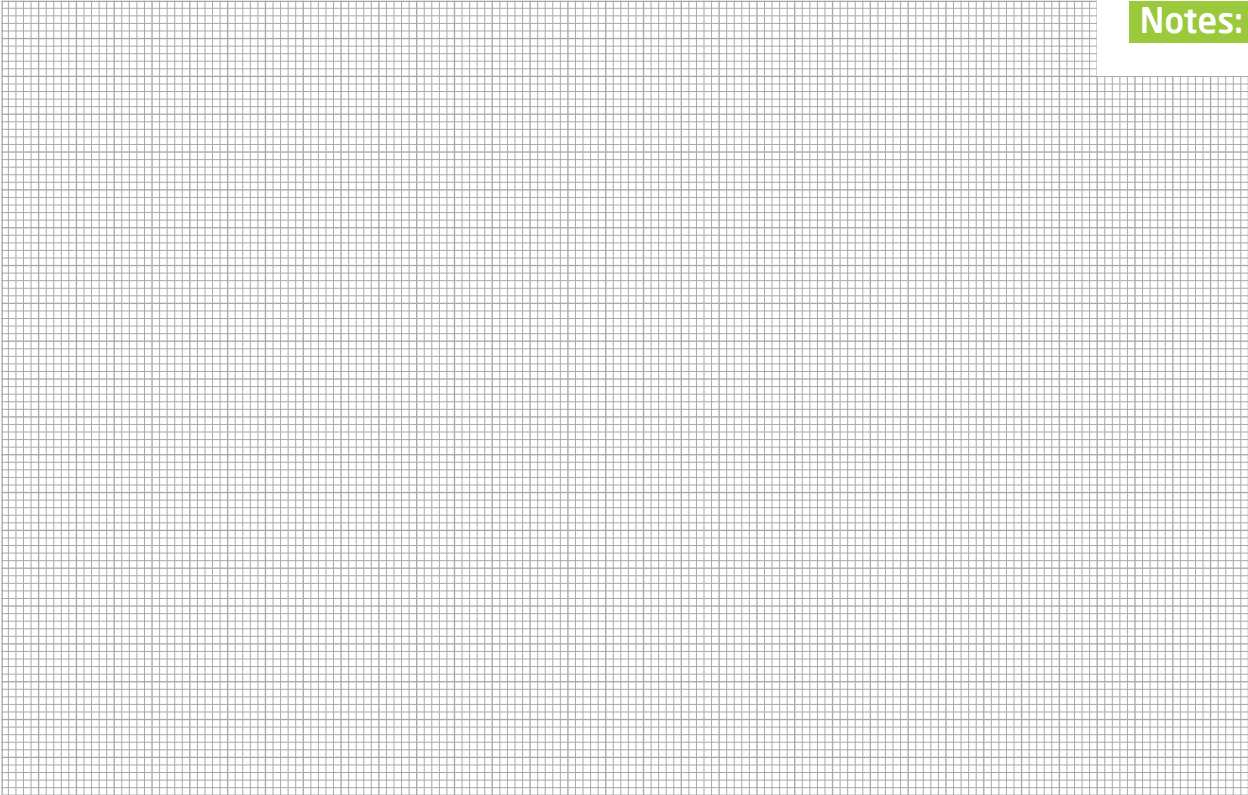
3. Pinout



■ Analog Lines
 ■ Interrupt Lines
 ■ SPI Lines
 ■ I2C Lines
 ■ UART lines
 ■ CAN lines
 ■ PWM lines

4. Dimensions





Notes:

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MINI-M4 for Stellaris
ver. 1.00





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Наши контакты:

Телефон: +7 812 627 14 35

Электронная почта: sales@st-electron.ru

Адрес: 198099, Санкт-Петербург,
Промышленная ул, дом № 19, литера Н,
помещение 100-Н Офис 331