

General Description

The MAX14900E octal high-speed, industrial, high-side switch evaluation kit (EV kit) is a fully assembled and tested surface-mount printed circuit board (PCB) that demonstrates the capabilities of the MAX14900E IC to drive industrial-grade signals.

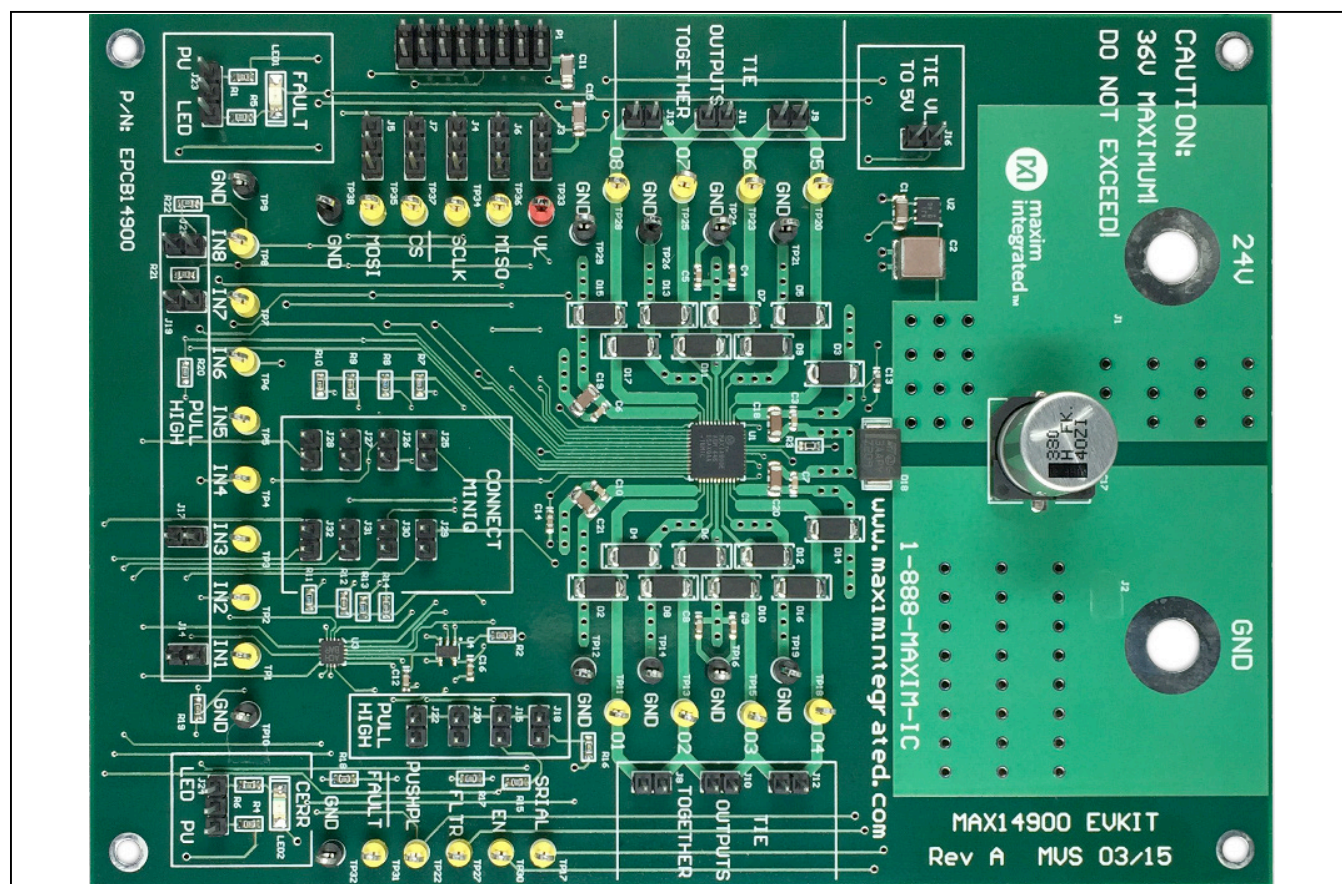
This EV kit demonstrates operation in all MAX14900E modes. In parallel mode, jumpers allow for arbitrary configuration. In serial mode, or parallel mode with serial monitoring, attach a control circuit to the appropriate test points, as detailed below.

Features

- Stand-Alone Operation in Parallel Mode
- SPI-Controlled for Serial Mode/Monitored-Parallel Mode
- Built-In 5V Regulator
- Surge-Compliance Clamp Diodes Included
- Fully Assembled and Tested

Ordering Information appears at end of data sheet.

MAX14900E EV Kit PCB Photo



Quick Start

Recommended Equipment

- MAX14900E EV kit
- 24V, 2A power supply
- Function generator
- Oscilloscope
- 50Ω, 15W (minimum) load resistor
- 5kΩ resistor
- Voltmeter
- Bench tie clips with spring clips on both ends

Procedure

The EV kit is fully assembled and tested. Follow the steps below to verify board operation:

- 1) Preset the 24V power supply to 24V and disable the power supply.
- 2) Connect the ground of the 24V power supply to jumper J2.
- 3) Connect the positive supply of the 24V power supply to J1.
- 4) Ensure that the shunt for J15 (EN) is installed.
- 5) Ensure that the shunt for J16 (connect V_L to 5V) is installed.
- 6) Ensure that J22 (PUSHPL) is installed.
- 7) Ensure that all other shunts are not installed.
- 8) Preset the function generator to pulse, 20ms pulse width, 500ms repetition rate, low-voltage 0V, high-voltage 5V, and disable the pulse generator.
- 9) Connect a 5kΩ resistor between O1 (TP11) and GND (TP12).
- 10) Connect an oscilloscope between O1 (TP11) and GND (TP12).
- 11) Connect the function generator between IIN1 (TP1) and GND (TP10).
- 12) Enable the 24V power supply.
- 13) Enable the function generator.
- 14) Observe the output waveform on the oscilloscope.
- 15) Disable the function generator.
- 16) Change the resistor from 5kΩ to 50Ω.
- 17) Remove the shunt on J22 (PUSHPL).
- 18) Enable the function generator.
- 19) Observe the output waveform on the oscilloscope.

Detailed Description

The MAX14900E octal, high-speed, industrial, high-side switch EV kit is a fully assembled and tested, surface-mount PCB that demonstrates the capabilities of the MAX14900E IC to drive industrial-grade signals.

This EV kit demonstrates operation in all MAX14900E modes. In parallel mode, jumpers allow for arbitrary configuration. In serial mode, or in parallel mode with serial monitoring, attach a control circuit to the appropriate test points. The EV kit operates from a single 24V (11V to 36V) main supply, and an optional logic supply. Through parallel or serial control, the IC switches the 24V supply to any combination of eight independent outputs. Besides the device itself, there are plenty of attach points, as well as numerous jumpers. The EV kit has little added circuitry.

TVS diode D18 protects the device from surges that may appear on the supply line through the clamp diodes. Note that D18 will likely be destroyed if the user applies a voltage greater than 36V on the 24V supply. Sixteen silicon diodes (D2–D17) protect the individual MAX14900E power outputs from severe inductive kickback events, as well as surges. A linear regulator, MAX5084 (U2), provides an optional default 5V in case the user does not wish to provide a logic-level supply externally. LED1 (FAULT) can be optionally configured to light whenever the device indicates a fault condition on its $\overline{\text{FAULT}}$ pin. LED2 (CERR) can be optionally configured to light when the device detects a CRC error in serial mode.

Input Power Supply

The EV kit obtains its primary power from a bench supply whose positive voltage attaches to J1 (24V), and whose return voltage attaches to J2 (GND). This supplies power only to the MAX14900E.

5V Power Supply

The device requires a 5V supply on pin 30 (V5), supplied by the 5V linear regulator (U2) for the user's convenience.

Logic Power Supply

Most of the device's digital pins have their input thresholds and their output drive levels defined by the voltage on pin 13 (V_L). This V_L supply can come from two places. First, the built-in 5V regulator can supply V_L by attaching a shunt to J16 (connect V_L to 5V), ensuring that no shunt is attached to J3 (V_L). When attaching external circuitry

to control and monitor the device, attach a voltage representing the external logic to TP33 (V_L), and attach a shunt to J3 (V_L) between the center and right posts.

Paralleling Outputs

The EV kit makes it easy to parallel up to four outputs together to deal with higher loads. J8, J10, and J12, when shunted, connect outputs O1–O4 together in various configurations. Similarly, J9, J11, and J13, when shunted, connect outputs O5–O8 in various configurations. To determine which outputs short to what, see [Table 1](#) for jumper and output information. The copper traces on the board are also evident from output to each jumper.

Dedicated Configuration Pins

J15 (EN), J20 (FLTR), and J22 (PUSHPL) set their respective pins high. When not shunted, these pins are driven logic-low from individual pulldowns inside the device.

Parallel Mode

To put the EV kit in parallel mode, ensure that no shunt is attached to J18 (SRIAL). Fault conditions can be monitored in two ways. First, attach a shunt between the right and center pins of J23. LED1 glows red whenever the device reports a fault condition. Otherwise, a fault condition can be monitored by attaching external monitoring circuitry to TP31 (FAULT). The MAX14900E $\overline{\text{FAULT}}$ pin is open-drain.

If the external circuitry attached to TP31 ($\overline{\text{FAULT}}$) has a pullup, ensure that J23 has no shunts attached. If the external circuitry has no pullup, attach a shunt to J23 between the left and center posts. External circuitry drives the parallel inputs at TP1–TP8. See [Table 3](#), describing how these control signals on TP1–TP8 determine the state of the outputs O1 through O8. In addition, three signals control how the TP1–TP8 control inputs are interpreted, as detailed in [Table 4](#).

Serial Mode Through External Circuitry

To drive the serial SPI interface of the device through external circuitry, ensure that J4–J7 each have shunts attached between the center and right posts. Then, attach the corresponding external SPI controls with TP34–TP37. The state of the SRIAL pin must be set appropriately. If running in monitored-parallel mode, SRIAL must be low (J18 has no shunt). If running in serial mode, J18 must be shunted.

Dual-Function Configuration Pins

When running in serial mode (not monitored-parallel mode or parallel mode), IN1, IN3, IN7, and IN8 become extra configuration pins. These pins are driven logic-low through weak internal pulldowns inside the device, but can be set high attaching shunts to J14, J17, J19, or J21.

Refer to the MAX14900E IC data sheet for a detailed description of these pin functions. Additionally, in serial mode, IN4 becomes an open-drain output, indicating a CRC error in a received serial-command stream. To see the state of this pin in serial mode, attach a shunt between the left and center posts of J24. LED2 glows red in case of a CRC error.

Table 1. Jumper Description (J3–J32)

| JUMPER | SHUNT POSITION | DESCRIPTION |
|--------|----------------|--|
| J3 | LEFT | Do not use |
| | RIGHT | V_L powered by TP33 (V_L) |
| | OPEN* | V_L powered by the 5V regulator (see J16) |
| J4 | LEFT | Do not use |
| | RIGHT | SCLK driven by signal on TP34 (SCLK) |
| | OPEN* | SCLK not driven |
| J5 | LEFT | Do not use |
| | RIGHT | SDI driven by signal on TP35 (MOSI) |
| | OPEN* | SDI not driven |
| J6 | LEFT | Do not use |
| | RIGHT | SDO drives signal on TP36 (MISO) |
| | OPEN* | SDO not driven |
| J7 | LEFT | Do not use |
| | RIGHT | \overline{CS} driven by signal on TP37 (\overline{CS}) |
| | OPEN* | \overline{CS} not driven |
| J8 | SHUNTED | Outputs TP11 (O1) and TP13 (O2) connected |
| | OPEN* | Outputs TP11 (O1) and TP13 (O2) separate |
| J9 | SHUNTED | Outputs TP20 (O5) and TP23 (O6) connected |
| | OPEN* | Outputs TP20 (O5) and TP23 (O6) separate |
| J10 | SHUNTED | Outputs TP13 (O2) and TP15 (O3) connected |
| | OPEN* | Outputs TP13 (O2) and TP15 (O3) separate |
| J11 | SHUNTED | Outputs TP23 (O6) and TP25 (O7) connected |
| | OPEN* | Outputs TP23 (O6) and TP25 (O7) separate |
| J12 | SHUNTED | Outputs TP15 (O3) and TP18 (O4) connected |
| | OPEN* | Outputs TP15 (O3) and TP18 (O4) separate |
| J13 | SHUNTED | Outputs TP25 (O7) and TP28 (O8) connected |
| | OPEN* | Outputs TP25 (O7) and TP28 (O8) separate |
| J14 | SHUNTED | TP1 (IN1) pulled to V_L |
| | OPEN* | TP1 (IN1) internally pulled weakly to ground |
| J15 | SHUNTED* | EN pulled to V_L |
| | OPEN | EN internally pulled weakly to ground |
| J16 | SHUNTED* | Power V_L from the built-in 5V regulator |
| | OPEN | Power V_L according to J3 |
| J17 | SHUNTED | TP3 (IN3) pulled to V_L |
| | OPEN* | TP3 (IN3) internally pulled weakly to ground |
| J18 | SHUNTED | SRIAL pulled to V_L |
| | OPEN* | SRIAL internally pulled weakly to ground |
| J19 | SHUNTED | TP7 (IN7) pulled to V_L |
| | OPEN* | TP7 (IN7) internally pulled weakly to ground |

Table 1. Jumper Description (J3–J32) (continued)

| JUMPER | SHUNT POSITION | DESCRIPTION |
|---------|----------------|--|
| J20 | SHUNTED | FLTR pulled to V_L |
| | OPEN* | FLTR internally pulled weakly to ground |
| J21 | SHUNTED | TP8 (IN8) pulled to V_L |
| | OPEN* | TP8 (IN8) internally pulled to ground |
| J22 | SHUNTED* | PUSHPL pulled to V_L |
| | OPEN | PUSHPL internally pulled to ground |
| J23 | LEFT | $\overline{\text{FAULT}}$ output pulled to V_L with 10K Ω |
| | RIGHT* | $\overline{\text{FAULT}}$ output state indicated by LED1 (FAULT) |
| | OPEN | $\overline{\text{FAULT}}$ output not pulled up |
| J24 | LEFT | IN4 pulled to V_L with 10K Ω |
| | RIGHT | IN4 state indicated by LED2 (CERR) |
| | OPEN* | IN4 not pulled up |
| J25-J32 | SHUNTED | Do not use |
| | OPEN* | Do not use |

*Default position.

Table 2. Test Point Description

| TEST POINT | DESCRIPTION |
|--------------|---------------------------------|
| TP1 (IN1) | Drive IN1 when in parallel mode |
| TP2 (IN2) | Drive IN2 when in parallel mode |
| TP3 (IN3) | Drive IN3 when in parallel mode |
| TP4 (IN4) | Drive IN4 when in parallel mode |
| TP5 (IN5) | Drive IN5 when in parallel mode |
| TP6 (IN6) | Drive IN6 when in parallel mode |
| TP7 (IN7) | Drive IN7 when in parallel mode |
| TP8 (IN8) | Drive IN8 when in parallel mode |
| TP9 (GND) | Ground attach point |
| TP10 (GND) | Ground attach point |
| TP11 (O1) | Connect a load to O1 here |
| TP12 (GND) | Connect the O1 return here |
| TP13 (O2) | Connect a load to O2 here |
| TP14 (GND) | Connect the O2 return here |
| TP15 (O3) | Connect a load to O3 here |
| TP16 (GND) | Connect the O3 return here |
| TP17 (SRIAL) | Drive SRIAL here |
| TP18 (O4) | Connect a load to O4 here |
| TP19 (GND) | Connect the O4 return here |
| TP20 (O5) | Connect a load to O5 here |

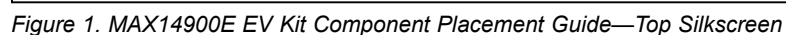
| TEST POINT | DESCRIPTION |
|------------------------------------|--|
| TP21 (GND) | Connect the O5 return here |
| TP22 (PUSHPL) | Drive PUSHPL here (see also J22) |
| TP23 (O6) | Connect a load to O6 here |
| TP24 (GND) | Connect the O6 return here |
| TP25 (O7) | Connect a load to O7 here |
| TP26 (GND) | Connect the O7 return here |
| TP27 (FLTR) | Drive FLTR here (see also J20) |
| TP28 (O8) | Connect a load to O8 here |
| TP29 (GND) | Connect the O8 return here |
| TP30 (EN) | Drive EN here (see also J15) |
| TP31 ($\overline{\text{FAULT}}$) | Indicate the state of $\overline{\text{FAULT}}$ here |
| TP32 (GND) | Digital interface ground attach point |
| TP33 (V_L) | Connect an external V_L supply here (see also J3 and J6) |
| TP34 (SCLK) | Drive optional SPI clock here |
| TP35 (MOSI) | Drive optional SPI MOSI here |
| TP36 (MISO) | Receive optional SPI MISO here |
| TP37 ($\overline{\text{CS}}$) | Drive optional SPI $\overline{\text{CS}}$ here |
| TP38 (GND) | SPI interface ground attach point |

Table 3. Parallel Driving Truth Table

| TP_ (IN_) | O_ STATE | |
|-----------|-----------|-----------|
| | PUSH-PULL | HIGH-SIDE |
| 0 | Low | Off |
| 1 | High | On |

Table 4. Global Configuration Inputs

| INPUT | CONFIGURATION FUNCTION |
|--------|---|
| FLTR | Enables anti-glitch filtering on all logic inputs TP1–TP8 0 = Glitch filtering disabled 1 = Glitch filtering enabled |
| PUSHPL | Configures all O1–O8 outputs as either push-pull or high-side 0 = All drivers high-side mode 1 = All drivers push-pull mode |
| EN | Enables normal operation of all O1–O8 outputs 0 = All outputs high impedance 1 = Normal operation |



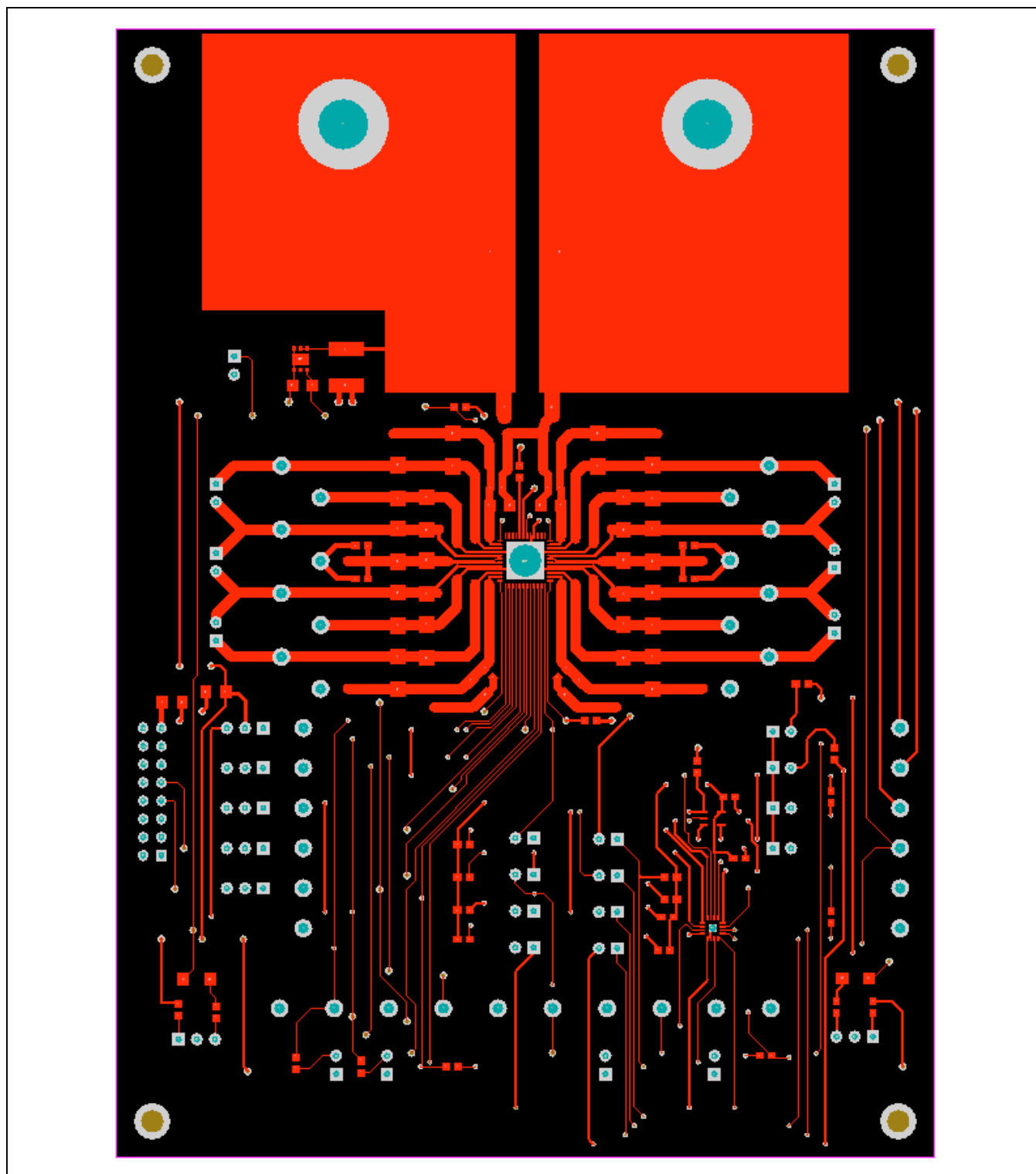


Figure 2. MAX14900E EV Kit PCB Layout—Top Layer

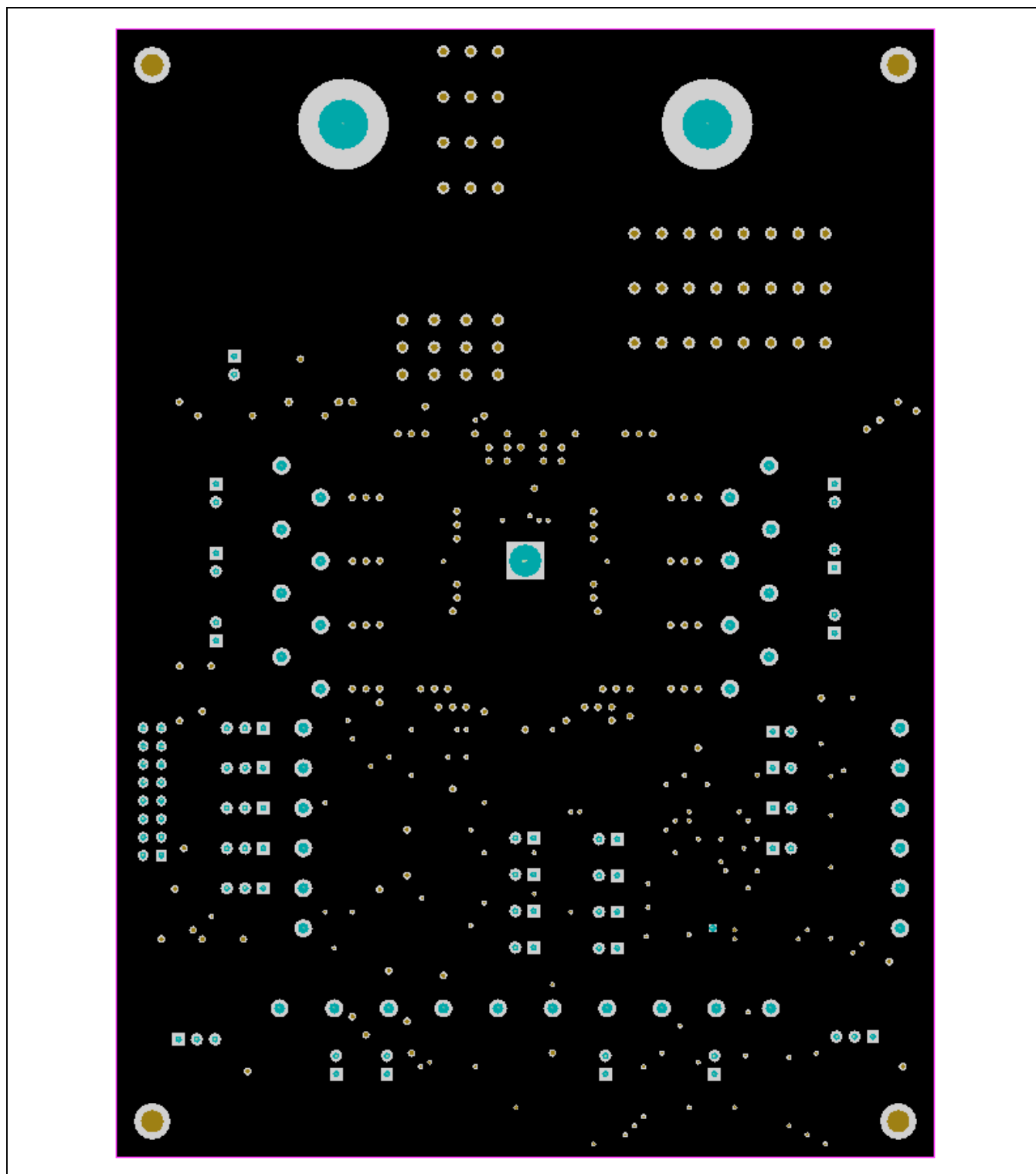


Figure 3. MAX14900E EV Kit PCB Layout, Internal Plane 1—GND

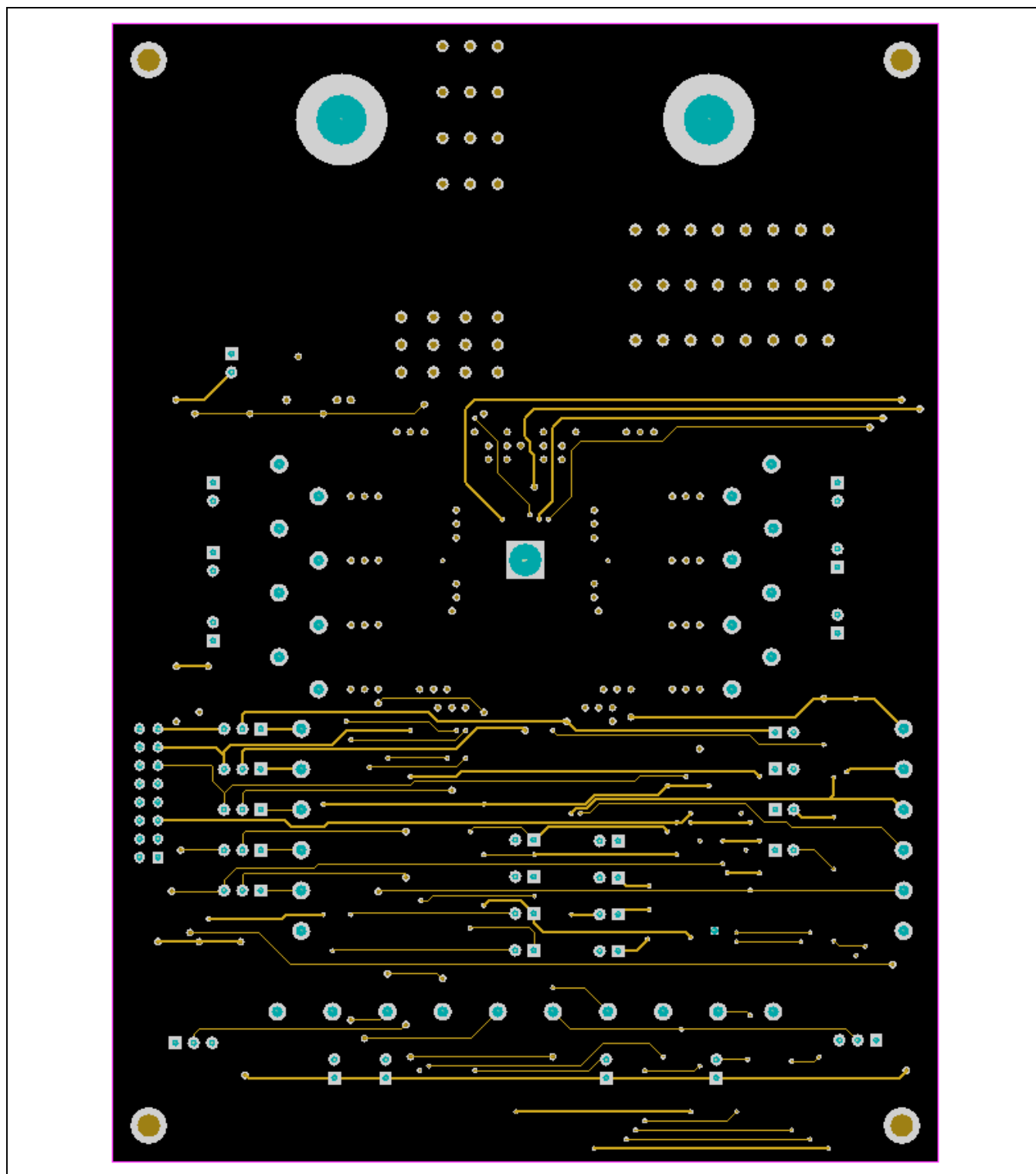


Figure 4. MAX14900E EV Kit PCB Layout—Mid-Layer 1

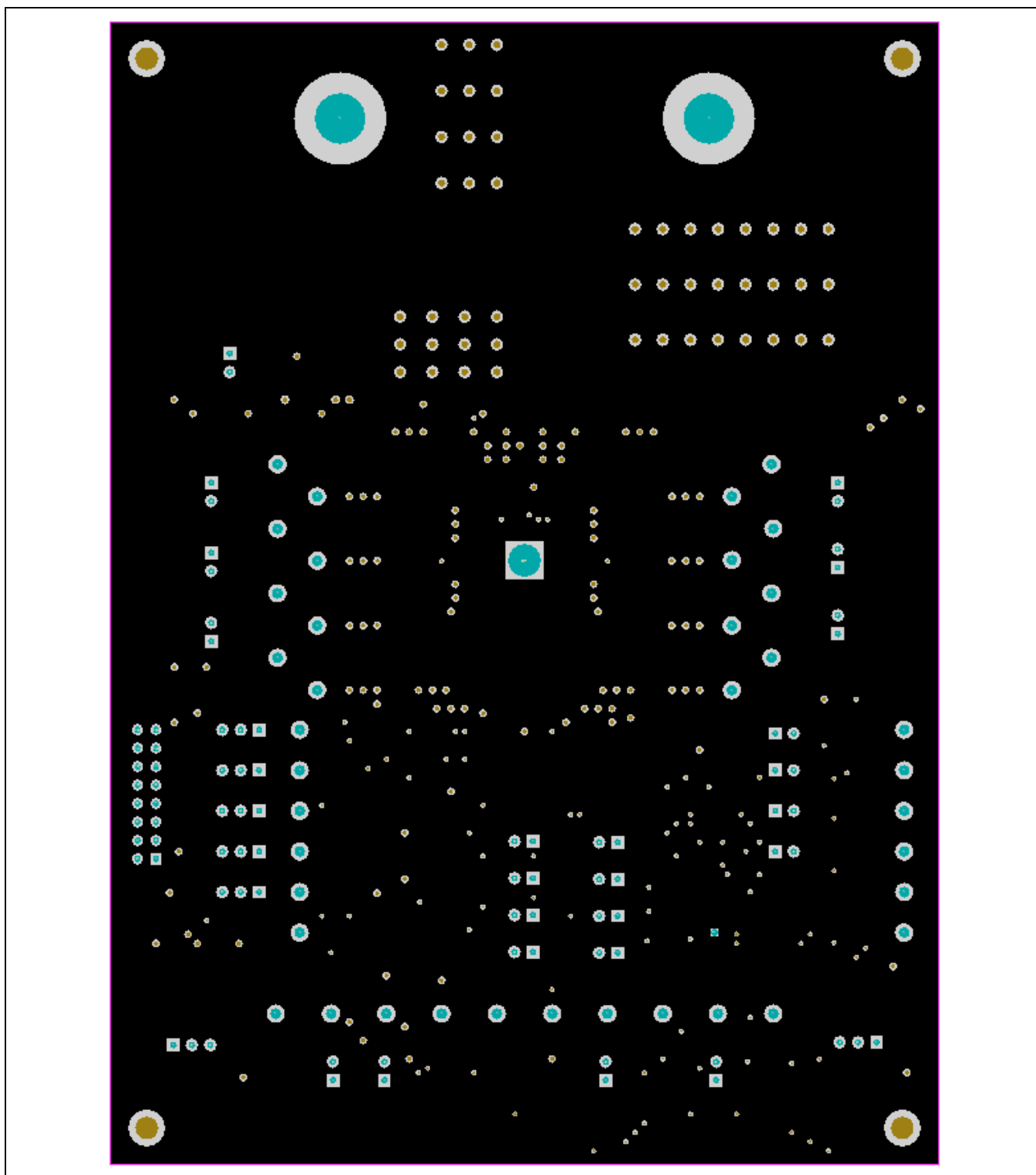


Figure 5. MAX14900E EV Kit PCB Layout, Internal Plane 2—GND

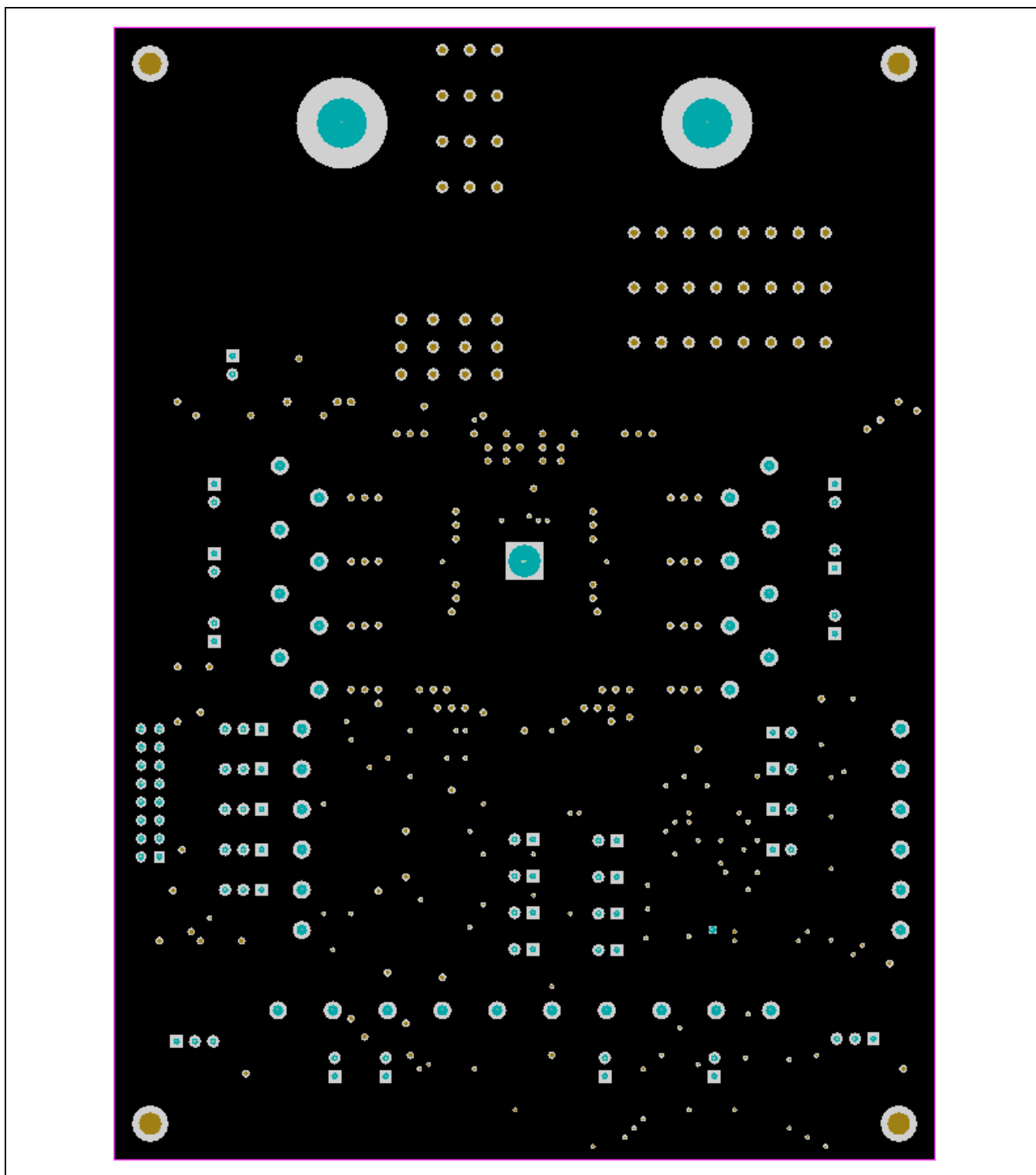


Figure 6. MAX14900E EV Kit PCB Layout, Internal Plane 3—V24V

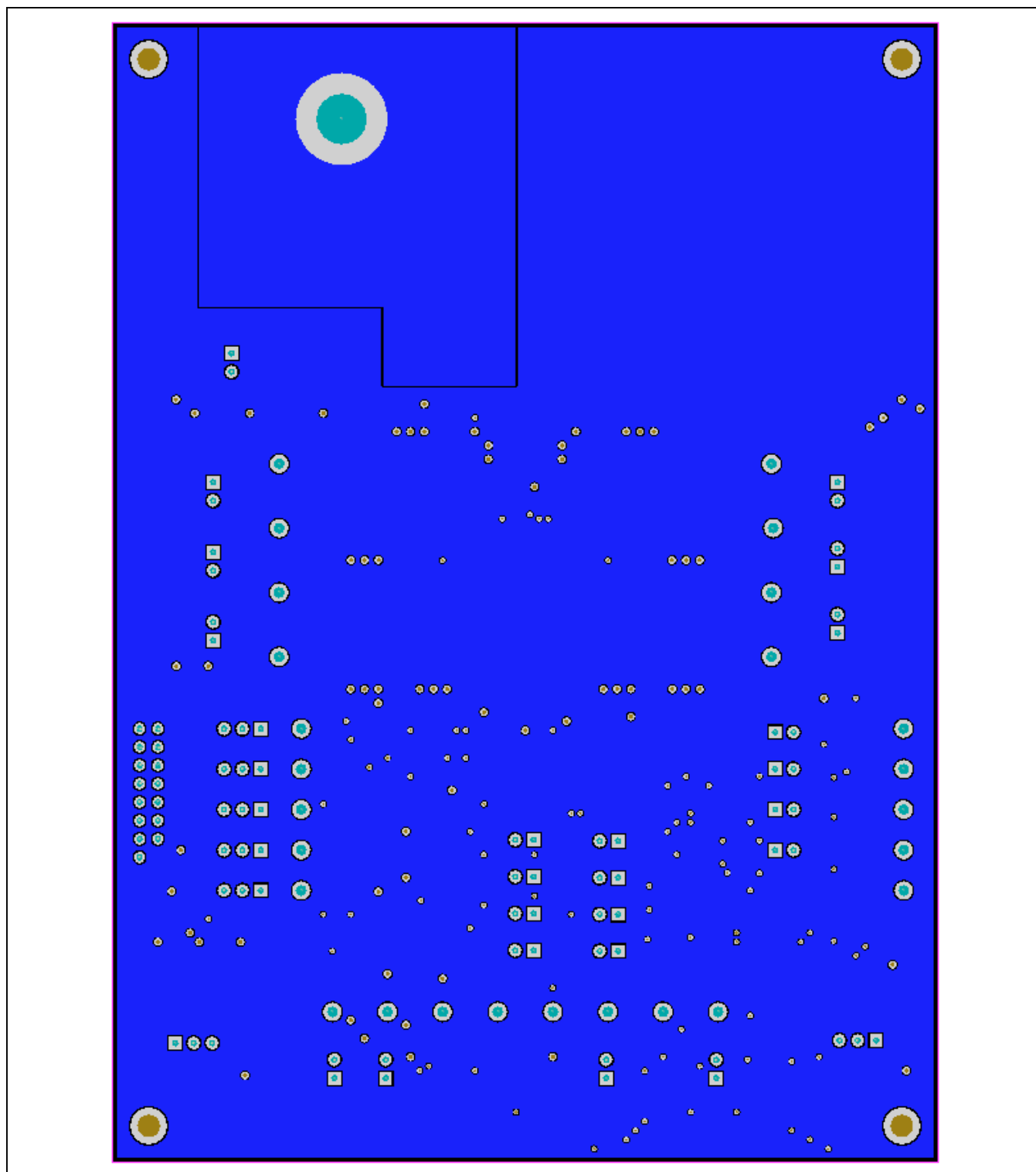


Figure 7. MAX14900E EV Kit Component Placement Guide—Bottom Layer

Component List and Schematic

See the following links for component information and schematics:

- [MAX14900E EV BOM](#)
- [MAX14900E EV Schematic](#)

Ordering Information

| PART | TYPE |
|-----------------|--------|
| MAX14900DEVBRD# | EV Kit |

#Denotes RoHS compliant.

Revision History

| REVISION NUMBER | REVISION DATE | DESCRIPTION | PAGES CHANGED |
|--------------------|------------------|-----------------|------------------|
| 0 | 5/15 | Initial release | — |

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.

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BILL OF MATERIALS (BOM)

| DESIGNATOR | QTY | DESCRIPTION | MFG | MFG P/N |
|--|-----|--------------------------------------|----------|--------------------|
| C1, C11, C15 | 3 | 10uF 10V 10% X5R 1206 | Kemet | C1206C106K8RACTU |
| C2 | 1 | 10uF 50V 20% X7R 2220 | TDK | C5750X7R1H106M |
| C3-C10 | 8 | 0.1uF 50V 10% X7R 0603 | Murata | GRM188R71H104KA93D |
| C12, C14, C16 | 3 | 0.1uF 16V 10% X7R 0603 | AVX | 0603YC104KAZ2A |
| C13 | 1 | 1uF 16V 10% X7R 0603 | AVX | 0603YC105KAT2A |
| C17 | 1 | Alum 330uF 20% SMD | Pana | EEEFK1H331AQ |
| C18-C21 | 4 | 1uF 50V 10% X7R 1206 | TDK | C3216X7R1H105K |
| D2-D17 | 16 | Diode Gen Purp 50V 2A SMA | On Semi | MURA205T3G |
| D18 | 1 | TVS Diode 33VWM 58VC SMC | STMicro | SM30T39AY |
| J1-J2 | 2 | STD Uninsulated Banana Jack | Pomona | Model 3267 |
| J3-J7, J23-J24 | 7 | Conn Header 50POS .100" Sngl Tin (3) | Various | |
| J8-J22, J25-J32 | 23 | Conn Header 50POS .100" Sngl Tin | Various | |
| LED1-LED2 | 2 | LED Red Clear 1206 | Lite-On | LTST-C150CKT |
| P1 | 1 | Conn Header .100 Dual 72POS | Various | |
| R1-R2, R4, R7-R22 | 19 | RES 10K Ohm 1/10W 5% 0603 | Pana | ERJ-3GEYJ103V |
| R3 | 1 | RES 56.0K Ohm 1/10W 1% 0603 | Pana | ERJ-3EKF5602V |
| R5-R6 | 2 | RES 1.0K Ohm 1/10W 5% 0603 | Pana | ERJ-3GEYJ102V |
| TP1-TP8, TP11, TP13, TP15, TP17-TP18, TP20, TP22-TP23, TP25, TP27-TP28, TP30-TP31, TP34-TP37 | 25 | Test Point PC Multi Purpose Yel | Keystone | 5014 |
| TP9-TP10, TP12, TP14, TP16, TP19, TP21, TP24, TP26, TP29, TP32, TP38 | 12 | Test Point PC Multi Purpose Blk | Keystone | 5011 |
| TP33 | 1 | Test Point PC Multi Purpose Red | Keystone | 5010 |
| U1 | 1 | MAX14900EAGM+ | Maxim | MAX14900EAGM+CKT |
| U2 | 1 | MAX5084ATT+ | Maxim | MAX5084ATT+ |
| U3 | 1 | MAX7317ATE+ | Maxim | MAX7317ATE+ |
| U4 | 1 | Bus Buff Tri-St N-Inv SOT23-5 | TI | SN74AHC1G125DBVR |



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