OMRON Ultrasonic Proximity Sensor

Rectangular Ultrasonic Proximity Sensor with Built-in Amplifier

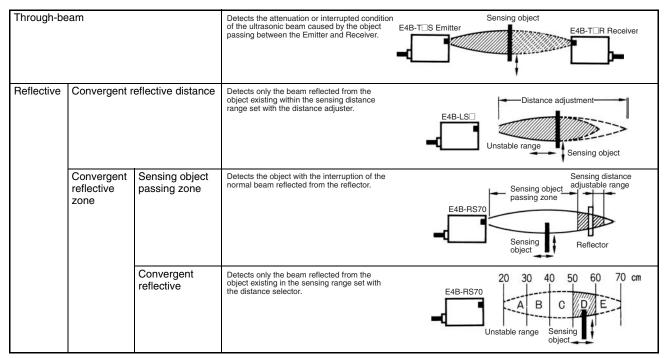
- Stable operation for a variety of objects regardless of color, transparency, or material (metallic or nonmetallic).
- Ultrasonic beam expansion of approx. 8°. Detect small objects of 20 x 20 mm min.
- With reflective models, setting sensing zones ensures detection without influence by the back-ground.



Ordering Information

Sensor (Refer to Dimensions on page 8.)

Output configuration	Sensing method		Sensing distance		Model	
DC switching NPN (normally open or closed selectable)	Through-beam		50 cm	n	E4B-TS50E4	
			:	100 cm	E4B-T1E4	
	Reflective	Convergent reflective (Distance adjustable)	5 to 20 cm		E4B-LS20E4	
				20 to 70 cm	E4B-LS70E4	
		Convergent reflective (Zone setting)		20 to 70 cm Sensing zone	E4B-RS70E4	

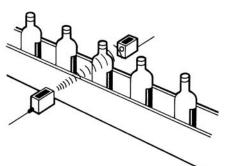


Note: An object may be detected due to multiple reflection if the object is in the unstable range where the distance adjuster is ineffective, in which case however, the detection of the object will not be stable. Therefore, do not attempt to use the E4B to detect an object in the unstable range.

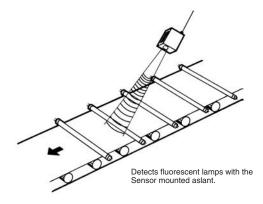
Application Examples

Detection of a variety of transparent bottles in bottle manufacturing, drink processing, and food processing lines

Detection of fluorescent lamps



Detects the absence or jamming of bottles



Specifications

Ratings/Characteristics

	Model	E4B-TS50E4	E4B-T1E4	E4B-LS20E4	E4B-LS70E4	E4B-RS70E4	
Sensing method		Through-beam		Convergent reflective distance		Convergent re- flective zone	
ltem	Sensing distance	50 cm	1 m	5 to 20 cm	20 to 60 cm (20 to 70 cm) (see note 1)	20 to 60 cm (20 to 70 cm) (see note 1) (in 10-cm divisions)	
Supply voltage		12 to 24 VDC \pm 10% (10.8 to 26.4 VDC) with a max. ripple \pm 10% (p-p)					
Current con- sumption	12 VDC	Emitter: 155 mA max. Receiver: 30 mA max.	Emitter: 70 mA max. Receiver: 30 mA max.	100 mA max.			
	24 VDC	Emitter: 80 mA max. Receiver: 30 mA max.	Emitter: 50 mA max. Receiver: 30 mA max.	50 mA max.			
Standard sensing	object	10 x 10 cm flat pla	te	4 x 4 cm flat plate			
Differential travel				20% max. of sensing distance 3		3 cm max.	
Directional angle (see note 2)		±8° max. Approx. 200 kHz					
	Ultrasonic oscillation frequency		I	I	1		
Response frequency (see note 4)		50 Hz	10 Hz	50 Hz	20 Hz		
Operating mode		Incident or interrupted (selectable)					
Control output		NPN, 100 mA at 30 VDC (with a residual voltage of 1.5 V max.) and an output resistance of 4.7 k Ω					
Indicators		SENSING indicator (red LED) and STABILITY indicator (green LED)					
Ultrasonic speed compensation		No Yes				Yes	
Ambient temperature		Operating: -10°C to 55°C					
Ambient humidity		Operating: 35% to 95%					
Temperature influence Voltage influence		±10% max. of sensing distance at 20°C in the temperature range of −10°C and 55°C ±5% max. of sensing distance at a voltage between 90% and 110% of the rated power supply volt- age					
Residual voltage		1.5 V max. under a load current of 100 mA and a cord length of 2 m					
Insulation resistar	nce	20 M Ω min. (at 500 VDC) between current carry parts and case					
Dielectric strength	Dielectric strength		1,000 V (50/60 Hz) for 1 min between current carry parts and case				
Vibration resistan	се	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions					
Shock resistance Destruction: 500 m/s ² (approx. 50G) 3 times each in X, Y, and Z directions.							
Degree of protection (see note 3)		IEC IP66 (JEM IP66 water resistive)					
Weight (with 2-m-long cord and Mounting Bracket)		Approx. 600 g (wit ceiver)	h Emitter and Re-	Approx. 300 g			
Materials		Case: ABS, Oscilla	ator: Ceramic				

Note: 1. These are the available sensing distances at an ambient temperature range between 0° C and 45° C.

- 2. This is the half-value angle obtainable at a signal of -6 dB.
- 3. The enclosure rating indicates the degree of protection of the case, which will depend on the operating condition.

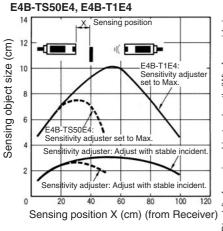
4. The response frequencies are values obtained with the E4B used for detecting a rotating propeller-shaped disc as shown on the right.

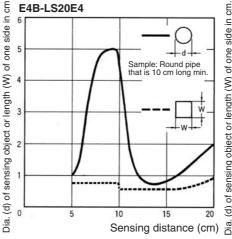
20cm

Space:Blade = 1:1

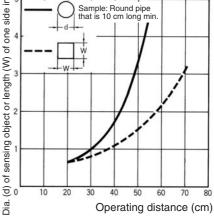
Engineering Data

Operating Distance vs. Sensing Object Size (Typical)





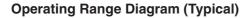
Note: The sensing method will change when the sensing distance exceeds 10 cm. As a result, the detectable diameters will change greatly.



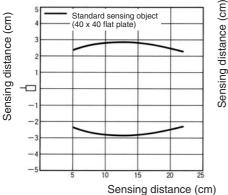
E4B-LS70E4, E4B-RS70E4

E4B

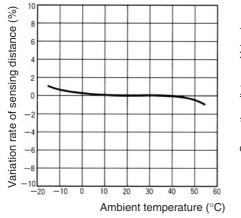
Note: The curve with the sensitivity adjuster set to maximum indicates the size of the sensing object.

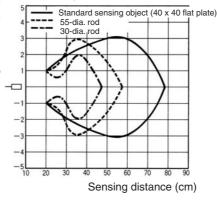


E4B-LS20E4



Ambient Temperature vs. Variation Rate of Sensing Distance (Typical) E4B-LS70E4, E4B-RS70E4

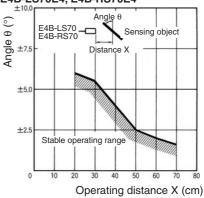


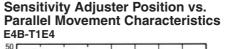


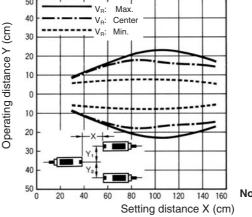
E4B-LS70E4, E4B-RS70E4

Object Angle (Typical) E4B-LS70E4, E4B-RS70E4

Operating Distance vs. Sensing







Note: Obtain the point that turns Y_1 and Y_2 ON while changing the sensing distance (X).

Adjustments

Indicators

1. STABILITY Indicator (Green)

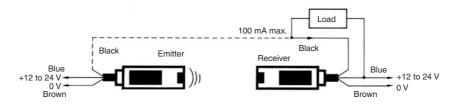
When this indicator is lit, the ultrasonic input into the Receiver is sufficient, or its interruption is small enough, to ensure the smooth operation of the E4B. Do not operate the E4B when this indicator is not lit.

2. SENSING Indicator (Red) When this indicator is lit, the Receiver has ultrasonic input.

Indicator of Through-beam Emitter

- 1. Incident Indicator
- Lit when there is ultrasonic input.

To use this indicator of the Emitter as an SENSING indicator like the indicator on the Receiver, connect the black lead wires of the Emitter and Receiver together.



- Note: Be sure not to make mistakes in polarity when connecting the above wires. In other words, both brown lead wires must connect to +DCV or 0 V and both blue lead wires must connect to 0 V or +DCV. Otherwise, the indicator of the Emitter will be lit when the ultrasonic beam is interrupted.
 - 2. Power Indicator

Lit when the E4B is turned ON. If the above connections are not possible (e.g., the Receiver and Emitter use different power supplies), this indicator will be used as a power indicator.

Connections of Black (White) Lead Wire of Emitter

Power connection example	Short-circuited
Brown: +DCV Blue: 0 V	0 V blue
Brown: 0 V Blue: DCV	+DCV blue

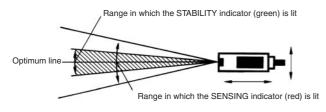
Note: The indicator will not be lit if the above wires are not connected correctly.

Beam Axis, Sensitivity, and Distance Adjustments

1. E4B-T1 and E4B-TS50 Through-beam Models

Set the SENSITIVITY adjuster of the Receiver to maximum.

Move the Emitter and Receiver vertically and horizontally until the SENSING indicator of the Receiver is lit and secure the Emitter and Receiver at the midpoint of the range within which the STA-BILITY indicator is lit.



Pass the sensing object through the sensing range and adjust the sensitivity so that the SENSING indicator turns ON and OFF according to the presence or absence of the sensing object while the STABILITY indicator is lit continuously.

If the STABILITY indicator is not lit while the Sensor is in operation, this may indicate a possible operational error. Check or readjust the sensitivity.

If the Emitter and Receiver are set at a distance shorter than the rated sensing distance, reduce the sensitivity to within the range in which the STABILITY indicator is lit. This will increase the immunity of the Sensor against noise.

The parallel movement characteristics (i.e., the mutual interference distance) and sensing object size vary with the sensitivity adjustment. Refer to *Engineering Data* and make the optimum adjustments.

2. E4B-LS20* and E4B-LS70 Convergent Reflective Distance Model

Locate the Sensor so that both the STABILITY and SENSING indicators will be lit when the sensing object is placed at the sensing position, and the STABILITY indicator will be lit and the SENSING indicator will turn OFF when the sensing object is removed.

Step	1	2	3	
Sensing	Sensing object	Sensing object	Sensing object	
Distance adjuster	10 5-20			
Adjustment procedure	Place the sensing object at the sens- ing position and turn the distance ad- juster clockwise gradually until both the SENSING and STABILITY indica- tors are lit.	Move the Emitter and Receiver verti- cally and horizontally and secure the Emitter and Receiver at the midpoint of the range within which the STABIL- ITY indicator is lit.	Remove the sensing object and check that the SENSING indicator is OFF and the STABILITY indicator is continuously lit.	

Note: If the STABILITY indicator is not lit while the Sensor is in operation, this indicates a possible operational error. Check or readjust the sensitivity.

Note: *E4B-LS20

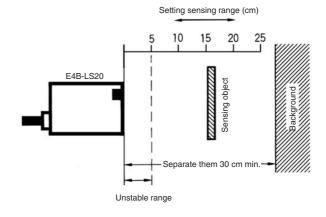
10 to 20 cm

The sensing distance is adjustable within a range of 10 to 20 cm with the distance adjuster.Sensing distancePosition of distance adjuster5 to 10 cmSet to the position 5-20. The distance range will be 5 to 23 cm in this case due to the characteristics of the ultrasonic beam.

trasonic reflection.

The adjuster can be set freely within a range of 10 to 20 cm. The object can be detected within a range of 5 to

10 cm in this case due to multiple ul-



General Use

Locate the Sensor so that both the STABILITY and SENSING indicators will be lit when the sensing object is placed at the sensing position and the STABILITY indicator will be lit and the SENSING indicator will be off when the sensing object is removed.

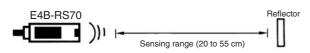
Step	1	2	3
Sensing		Sensing object	Sensing object
Distance selector			
Adjustment procedure	Place the sensing object at the sens- ing position and turn the distance se- lector clockwise gradually until both the SENSING and STABILITY indica- tors are lit.	Move the Emitter and Receiver verti- cally and horizontally and secure the Emitter and Receiver at the midpoint of the range within which the STABIL- ITY indicator is lit.	Remove the sensing object and check that the SENSING indicator is OFF and the STABILITY indicator is continuously lit.

Note: 1. If the STABILITY indicator is not lit while the Sensor is in operation, this indicates a possible operational error. Check or readjust the sensitivity.

2. If the background object is within a distance of 1.5 m from the sensing head, the SENSING indicator may be lit and the STABIL-ITY indicator may not be lit in spite of the absence of the sensing object. In such a case, give priority to the adjustment of the indicators with the sensing object located at the sensing position.

Retroreflective Use

The retroreflective model assures the stable detection of objects under irregular and unstable reflection conditions (e.g., if the sensing objects are different in surface or size, if they are passed through diagonally, or if they are warped or move in a wave-like way).





 ${\it \ell}:$ Near the midpoint of the sensing range (e.g., 45, 55, or 65 cm)

The Reflector must be at least 4 x 4 cm in size and made of a material that is efficiently reflective (such as a metal plate). The E39-R1 for photomicrosensors is ideal.

Be sure that the reflector is not set within the sensing range.

Set the distance selector to the desired position, fix the reflector around the midpoint of the set sensing range, and check that both the SENSING and STABILITY indicators are lit.

Step	1	2	3
Sensing	جرامی کار	- ()))) Beflector	B A Reflector
Distance selector			
Adjustment procedure	Set the distance selector to the de- sired zone position, mount the Reflec- tor at or near the midpoint of the set zone, and confirm that both the STA- BILITY and SENSING indicators are lit.	Move the Emitter and Receiver verti- cally and horizontally and secure the Emitter and Receiver at the midpoint of the range within which the STABIL- ITY indicator is lit.	Remove the sensing object and check that the SENSING indicator is OFF and the STABILITY indicator is continuously lit.

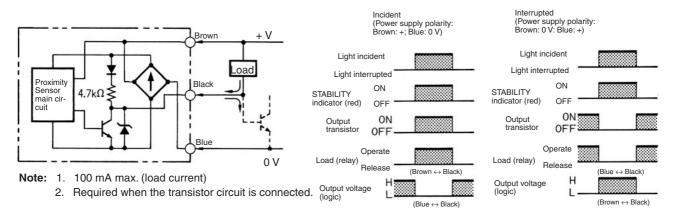
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- Note: 1. If the STABILITY indicator is not lit while the Sensor is in operation, this indicates a possible operational error. Check or readjust the sensitivity.
 - 2. If the sensing object is in position A parallel to the Reflector as shown above, the SENSING indicator may be lit and the STA-BILITY indicator may not be lit depending on the position of the sensing object. In such a case, give priority to the adjustment of the STABILITY indicator when the beam is incident by means of the reflector.

Operation

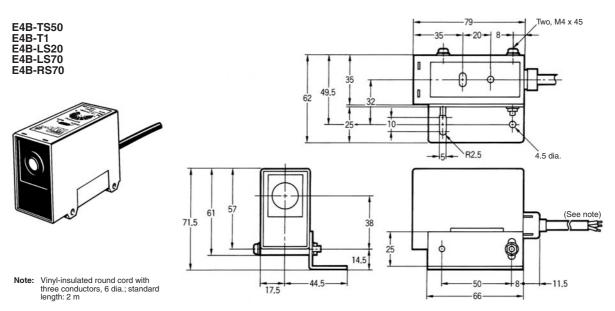
Output Circuits

NPN Models Switching DC



Dimensions

Note: All units are in millimeters unless otherwise indicated



Precautions

Correct Use

Sensor Mounting Angle

If the E4B is in level control or distance control of sensing objects, the stability of signal detection will depend on the sensing surface condition of the objects. Considering the repose angle of the objects, mount the E4B so that the ultrasonic beam and the sensing surface of each object meet at right angles to each other.

Surrounding Objects

Make sure that the Sensor is free from surrounding objects that reflect the ultrasonic beam diffusion, otherwise the Sensor may malfunction. In particular, pay the utmost attention so that no side lobe of the ultrasonic beam will be reflected by such objects.

Mounting

Securely mount the E4B by using the nuts provided with the E4B or the mounting holes of the E4B. Refer to *Dimensions* for details.

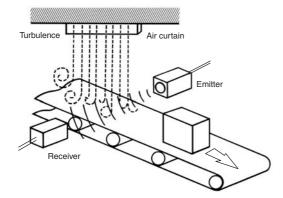
Do not strike the Sensor with any hammer or other object, otherwise the E4B will no longer be water-resistant.

If the E4B is not mounted securely, the E4B may be damaged by vibration or may not detect sensing objects accurately due to a possible change in the mounting position.

Environmental Conditions

Do not use the E4B at a temperature exceeding the rated range or outdoors, otherwise the reliability and life of the E4B will decrease.

The Ultrasonic Reflective Sensor utilizes the air as a beam transmission media. Do not use the E4B in places with radical convection or extreme local temperature changes. For example, if there is a hot air curtain that causes turbulence within the sensing area, the E4B may malfunction.



The jetting sound of air nozzles includes noise of a wide frequency range, which will affect the operation of the E4B. Do not use an air nozzle near the E4B.

The sensing distance of the E4B will decrease if there is any water drops on the surface of the emitter or receiver.

The through-beam model may not detect any objects if there is any object absorbing sound, such as powder and cotton, on the surface of the emitter or receiver.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS. To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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In the interest of product improvement, specifications are subject to change without notice.

OMRON Corporation Industrial Automation Company

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DIMENSIONS AND WEIGHTS

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